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TRANSPORTATION Engg.

1. Highway planning and geometric design of Highways.
2. pavement material characteristics and design of pavement
3. Traffic Engineering.

UNIT - XVI

Traffic Engineering:

1. Traffic surveys
2. Traffic census

Traffic surveys:-

Objectives :-

1. It is helping in geometric design features
2. Traffic control for safety. 
3. Efficient traffic movement. 

1. Traffic volume study:-

IS the number of vehicles crossing at a particular section of the road per unit time. (veh/hr)

2. passenger car unit (PCU):-

IT is a conversion factor converting all the classification of vehicle into single unit.

PCU Values:-

car - 1

2W - 0.5

3W - 1.5

Buses - 3

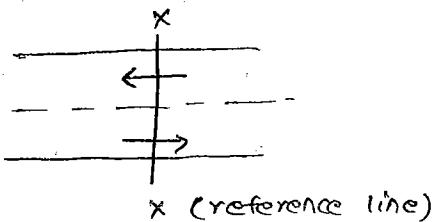
Heavy weight trucks - 4

Bullock cart - 6 (or) 8

Methods of conducting traffic volume study:-

1. Manual method:-

Time	SMW		FMW		
	Cycle	Auto	2W	3W	car
8 - 8:30			2		1



Advantages:-

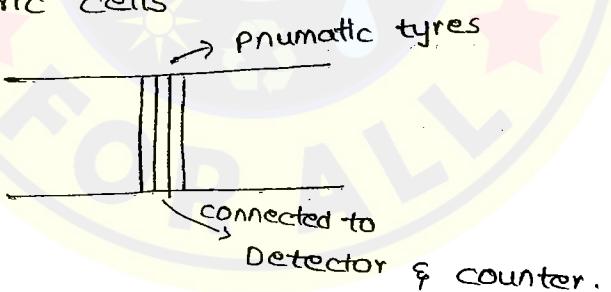
1. Classification of vehicles is possible.
2. Directional movement of traffic at the intersection is possible.

3. Disadvantages:-

1. Longer periods is not possible
2. Difficult to conduct in bad weather.

2. Mechanical method:-

By using instruments like Magnetic detectors, Ultrasonic device, photo electric cells



These are called Automatic detecting counters.

Advantages:-

1. Longer period is possible
2. possible to conduct in bad weather.

Disadvantages:-

1. classification of vehicle is not possible
2. It is not possible the directional movement of traffic at the intersection.

* Hourly volume:-

7 days per 1 hour interval

$$7 \times 24 = 168 \text{ hourly volume.}$$

Max.	S.NO.	Hourly volume
!	1	1st highest hourly volume
!	2	2nd highest hourly volume

→ the 30th hourly volume is considered as designed hourly volume for geometric features of Highway.

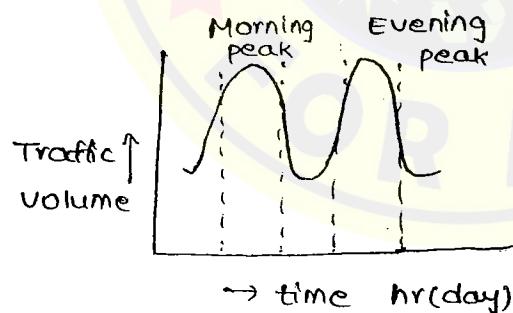
Representation of traffic volume data:-

1. AADT - Annual Average Daily traffic.

$$\text{Total number of vehicles moving in 1 year} \\ = \frac{\text{No. of days in a year}}{\text{Number of vehicles moving in survey period}}$$

2. ADT - Average Daily traffic.

$$= \frac{\text{Number of vehicles moving in survey period}}{\text{No. of days in survey}}$$



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Speed study:-

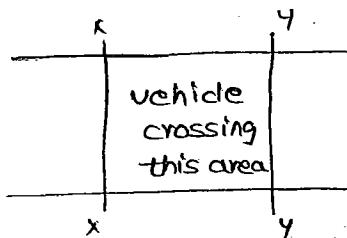
1. Spot speed study
2. Speed and Delay study

Spot speed study:-

The instantaneous speed of a vehicle at a particular section of the road is known as spot speed.

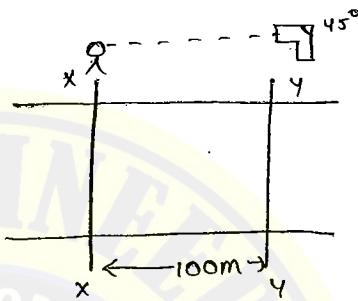
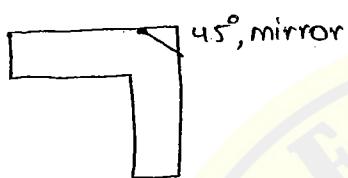
Methods of spot speed study:-

1. pavement marking method:-



2. Enoscope method:-

Enoscope is a L-shaped mirror box, mirror is placed at an angle of 45°



3. Radar gun:-

It works under the principle of "Laser rays".

Cumulative Frequency table:-

S.NO.	Speed class (or) Range (kmph)	Mid point of speed	No. of vehicles and Frequency	% frequency	cumulative % frequency
1.	20 - 25	22.5	veh 2	x	x
2.	26 - 30	28.5	veh 3	y	x+y
3.	31 - 35	:	:		
4.	36 - 40	:	veh 1		

$$\text{veh } 1 = 36.5 \text{ kmph}$$

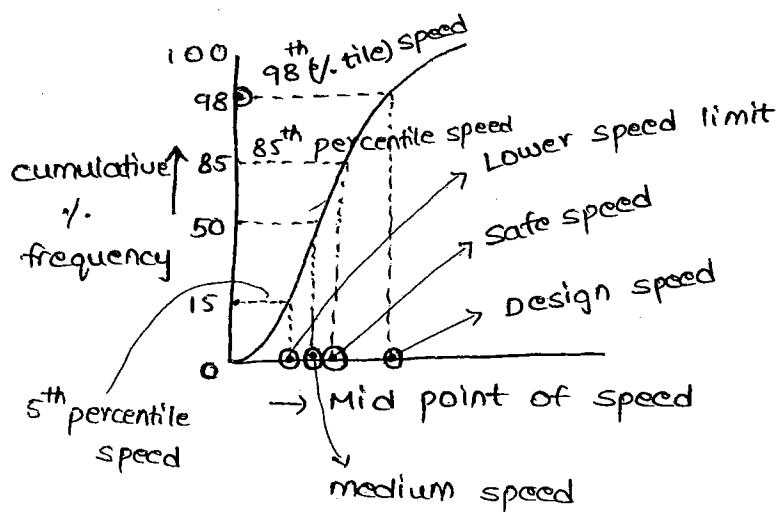
$$\text{veh } 2 = 23 \text{ kmph}$$

$$\text{veh } 3 = 83 \text{ kmph}$$

$$\text{veh } 4 = :$$

○ draw a graph between cumulative % frequency and mid point of speed:-

(3)



98th percentile speed:-

Speed below which 98% of vehicles travel. It is used as design speed in geometric features of highway.

85th percentile speed:-

The speed below 85% of vehicles travel. It is used for safe speed finding the speed limits for traffic regulation therefore it is known as safe speed.

15th percentile speed:-

The speed below 15% of vehicles travel. It is used to find the lower speed limit on major highway facility such as express way

Average speed or Mean speed:-

i. Time Mean speed:-

The arithmetic average of spot speeds of vehicles $v_1, v_2, v_3, \dots, v_n$ are spot speed of vehicles

$$\text{speed} = \frac{v_1 + v_2 + v_3 + \dots + v_n}{n}$$

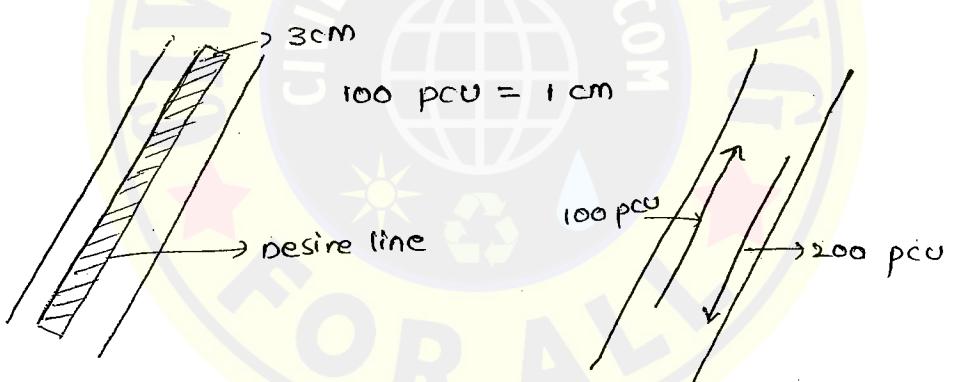
Speed and Delay study:-

It gives running speed overall speed variation of speed amount of delay frequency of delay and causes of delay between the two stations. Generally delays are two types i) Fixed delay ii) Operational delay.

→ Test car method (or) moving car method are best suitable for speed and delay study.

Origin-Destination study:-

1. For planning of a transportation facility such as Metro rail.
2. To plan the road network.
3. plan the schedule of different modes of transportation.
4. The home interview method is best suitable
5. Desire lines are plotted in this survey.



→ width of desire line is proportional to the number of trips in both directions

Intersection:-

It is classified into two types

- 1) Intersection at Grade
- 2) Grade separated Intersection

↓
where the traffic is living at different levels

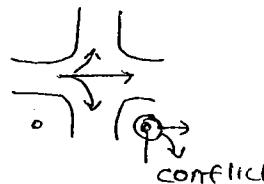
Ex:- Fly overs, cloverleaf.

Intersection at grade:-

Traffic is moving at one level at intersection.

Different types of intersection at grade are:

1. T-intersection. T
2. cross - intersection +
3. staggered intersection 
4. skewed intersection Y
5. skewed cross Intersection X
6. skewed staggered intersection 
7. 4 - intersection Y
8. Multiple Intersection 



Consider a right angle and controlled intersection :-

1. If both the routes are two way traffic the total no. of conflict points are 24.
2. If one of the road is one way the total number of conflict points are 11.
3. If both the roads are one way the number of conflict points are 6.

Consider

Ex:-1. Two major roads crossing a urban area forming a uncontrolled intersection. The number of conflict points when both the roads are one way is 'x' and when both the roads are two way is 'y' then the ratio x to y is

A. $\frac{x}{y} = \frac{6}{24} = 0.25$

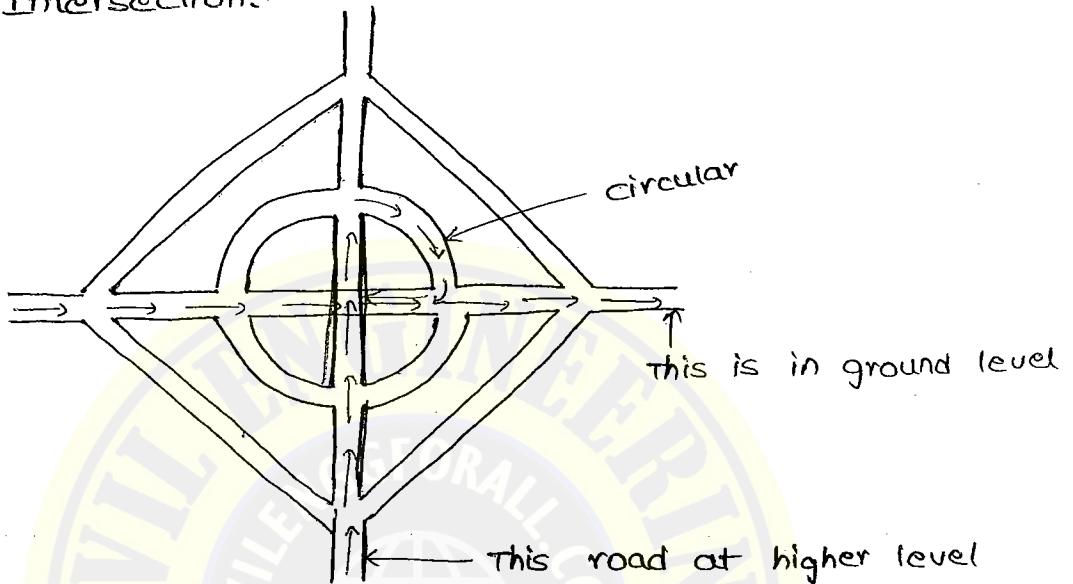
2. Grade separated intersection:-

cloverleaf intersection:-

1. Traffic is moving at different levels at the intersection such intersection is called grade separated intersection.

Ex:- cloverleaf intersection

cloverleaf intersection:-



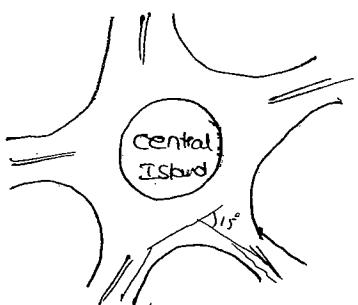
→ In clover leaf intersection, conflict points is zero and delays are zero.

Limitations:-

1. Initial cost is high.

Rotary intersection (^{Ex :- of} Intersection at grade) :-

1. All the vehicles at rotary intersection are move in one direction.



→ The terms used for the construction of Rotary Intersection (6)

1. Design speed - 30 km for urban, 40 km for rural.
2. Weaving angle - the angle between the path of a vehicle entering the rotary and another vehicle leaving the rotary at adjacent road.

For smooth flow of traffic the weaving angle should be small but not less than 15° .

3. Weaving distance (or) weaving length (L) :-

The distance between two adjacent intersecting roads. The minimum weaving length is 30m for urban areas and minimum weaving length is 45 m for rural areas.

4. Practical capacity of the rotary :-

$$Q_p = \frac{280W \left(1 + \frac{e}{w}\right) \left(1 + \frac{P}{3}\right)}{1 + \frac{w}{L}}$$

w = width of weaving section.

e = avg. width of the road at the entry and exit.

P = proportion of weaving traffic

P = turning and crossing traffic

total traffic

L = weaving distance and weaving length.

Weaving means merging and diverging of vehicles.

The practical capacity of the rotary is dependent on the minimum capacity of the individual weaving section.

Super elevation is not required at the rotary intersection.

Radius at the exist should be more than the radius at the entry

- Rotary is unsuitable i) if pedestrian traffic is large.
 ii) Having more number of slow moving vehicles.
 iii) Having more than 7 approach roads.

Ex:- A rotary is provided with average entry width 8.4m width of weaving section 14m, length of weaving section 35m. The crossing traffic and total traffic on the weaving section are 1000 and 2000 PCU/hr. The practical capacity of rotary

$$A. Q_p = \frac{280W \left(1 + \frac{e}{w}\right) \left(1 - \frac{p}{3}\right)}{1 + \frac{w}{L}}$$

$$w = 14 \text{ m}$$

$$L = 35 \text{ m}$$

$$e = 8.4 \text{ m}$$

$$p = \frac{\text{crossing traffic}}{\text{total traffic}} = \frac{1000}{2000} = 0.5$$

$$Q_p = \frac{280 \times 14 \left(1 + \frac{8.4}{14}\right) \left(1 - \frac{0.5}{3}\right)}{1 + \frac{14}{35}}$$

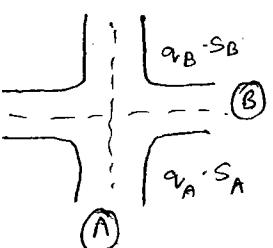
$$= 3733.33 \text{ PCU/hr.}$$

Signal Design:-

1. Fixed type (FT) signals:-

Websters approach for design of FT signals.

Consider a cross intersection where a straight traffic is permitted.



1. conduct traffic volume study to find normal flow and saturation flow (s). (7)
2. Normal flow is the traffic volume during design hours are peak hours. (PCU/hr)
3. Saturation flow is calculated by using $525w$, where 'w' is width of the road in meters. (PCU/hr)

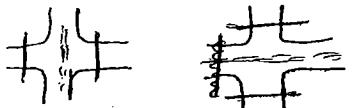
Ex:- Find the ratio between Normal flow to saturation flow.

A) $y_a = \frac{q_a}{s_a}, y_b = \frac{q_b}{s_b}$

$$y = y_a + y_b$$

4. Total lost time per cycle = $2\pi + R$

$$L = 2\pi + R$$



where, π = no. of faces

5. R = All-red time for pedestrian crossing

5. Optical cycle signal length, $c_o = \frac{1.5 L + 5}{1 - 4}$

6. Green time for A-road, $G_A = \frac{y_a}{4} (c_o - L)$

7. Green time for B-road, $G_B = \frac{y_b}{4} (c_o - L)$

8. Green time for A-road \approx Red time of B-road

9. Green time for B-road \approx Red time of A-road.

10. provide amber time two seconds for each face.

11. The traffic volume moving in the time period of optimum signal cycle length as green time, is known as saturation flow.

Ex:-) In signal design the sum of ratios of normal flows to saturation flow is 0.5 and the total lost time per cycle is 10 sec. The optimum cycle length in sec is

A) $y = 0.5$

$$L = 10 \text{ sec}$$

$$\begin{aligned} C_0 &= \frac{1.5L + 5}{1-y} \\ &= \frac{1.5(10) + 5}{1-0.5} \\ &= \frac{20}{0.5} \end{aligned}$$

$$C_0 = 40 \text{ sec}$$

Ex:-) For designing a two phase fixed time signal at an intersection having north south and east west roads where straight traffic only permitted. The time lost per cycle is 12 sec the cycle length as per webster approach.

A)

	N	S	E	W
Design hour volume (PCU/hr)	1000	700	900	550
Saturation flow (PCU/hr)	2500	2500	3000	3000

$$\left. \begin{array}{l} A) \quad y_{\text{north}} = \frac{1000}{2500} = 0.4 \\ \quad \quad \quad y_{\text{south}} = \frac{700}{2500} = 0.28 \\ \quad \quad \quad y_{\text{east}} = \frac{900}{3000} = 0.3 \\ \quad \quad \quad y_{\text{west}} = \frac{550}{3000} = 0.18 \end{array} \right\} \begin{array}{l} y_{N-S} = 0.4 \text{ (max value)} \\ y_{E-W} = 0.3 \text{ (max value)} \end{array}$$

$$y = y_{N-S} + y_{E-W}$$

$$= 0.4 + 0.3$$

$$y = 0.7$$

$$C_0 = \frac{1.5L + 5}{1 - q}$$

$$= \frac{1.5(12) + 5}{1 - 0.7}$$

$$= 76.6 \text{ sec.}$$

$\therefore L = 12 \text{ sec.}$

(8)

Ex:- An intersection approach the normal flow rate 1000 veh/hr and saturation flow rate 2800 veh/hr, optimum signal cycle length is 90 sec, Green ratio for the given approach road 0.55. What is the critical capacity of the approach road and average delay per vehicle under this conditions.

A) Normal flow, $q = 1000 \text{ veh/hr}$

$$C_0 = 90 \text{ sec}$$

Saturation flow, $s = 2800 \text{ veh/hr}$

The capacity of the road = saturation flow x Green ratio

$$C = s \times \left(\frac{g_{\text{ratio}}}{C_0} \right)$$

$$= 2800 \times 0.55$$

$$= 1540 \text{ PCU/hr}$$

$$\text{Green ratio} = \frac{g}{C_0}$$

g = effective green time

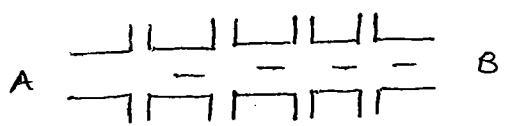
C_0 = Optimum signal cycle length

$$\rightarrow \text{effective green time, } g = G_{\text{time}} + A_{\text{time}}^{\text{Amber}} - \text{Total lost time}$$

$$= G_{\text{time}} + A_{\text{time}} - T_L (\text{start up lost time} + \text{clearance lost time})$$

$$\begin{aligned} \text{Delay (d)} &= \frac{C_0}{2} \left[1 - \frac{g}{C_0} \right]^2 \\ &\quad \times \frac{1 - \frac{\text{Normal flow (q)}}{\text{Saturation flow (s)}}}{1 - \frac{1000}{2800}} \\ &= \frac{90}{2} \left[1 - 0.55 \right]^2 \\ &\quad \times \frac{1 - \frac{1000}{2800}}{1 - \frac{1000}{2800}} \\ &= 14.57 \text{ sec} \end{aligned}$$

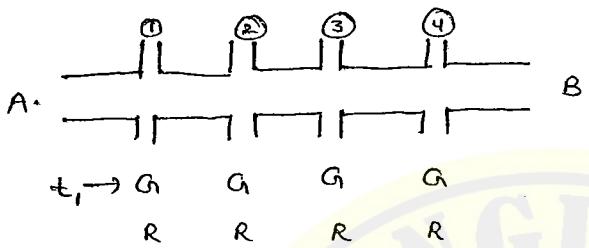
Signal Coordination :-



There are four types of signal coordination is there:

1. simultaneous system:-

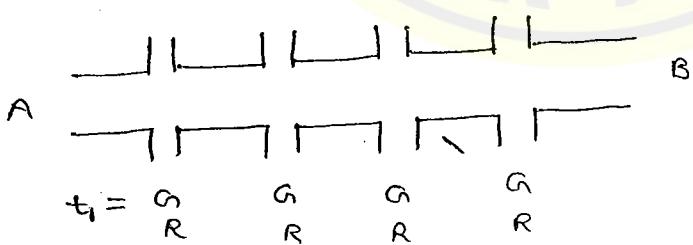
In this system it shows the same indication of the same time at all the intersections.



conditions:-

1. All the intersection should be provided with fixed time signals. (F.T)
 2. optimum signal cycle length (c_0) should be same for all the intersection.
2. Alternate system:-

A group of signals shows the opposite direction indication at the same time.

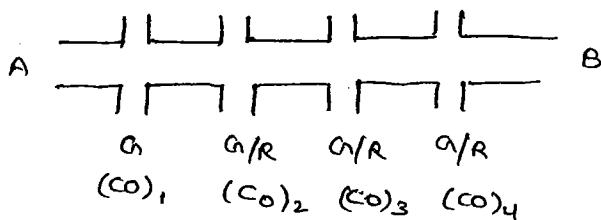


Conditions:-

1. All the intersection should be provided with fixed time signals (F.T)
2. optimum signal cycle length (c_0) should be same for all the intersection.

3. simple progressive system:-

Each signal system is a fixed time signal but having different signal cycle length at different intersections.



conditions:-

1. All the intersections are provided with fixed time signals.
2. "c₀" for all the intersection is not same for all intersections.
3. Flexible progressive system:-

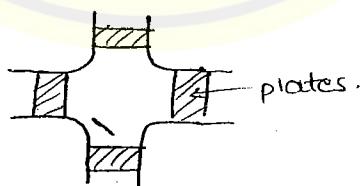
It is possible to change length of the cycle and time schedule @ each intersection.

Conditions:-

1. All the intersection sections are not provided with fixed time signals.
2. c₀ at a particular intersection will not same.

Note:-

Most efficient system is flexible progressive system.



Capacity of the Highway:-

The maximum no. of vehicles that the road can accomodate.

Design capacity:-

The maximum no. of vehicles that can pass at particular section of road during 1 hour without any delay under given road way conditions and traffic conditions.

$$C = \frac{1000v}{s}$$

v = speed vehicle in kmph

s = space head way in m

C = capacity in PCU/hr/lane (or) veh/hr/lane

Space head way:-

Distance between two successive vehicles in a traffic stream.

$$s = SSD + L \text{ (vehicle length)}$$

$$s = (\text{Lag distance} + \text{Break distance}) + L$$

$$s = (0.278 vt + \frac{v^2}{254f}) + L$$

where

v = velocity in kmph

t = total reaction time of the driver in sec

f = longitudinal coefficient of friction.

Ex:- A single line to uni-direction highway has a design speed of 65 kmph. The total reaction time of the driver 2.5 sec. Avg. length of the vehicle 5m. The coefficient of longitudinal section ($f = 0.4$). The capacity of the road length of veh/hr/lane (or) PCU/hr/lane.

A) Given speed = 65 kmph $L = 5 \text{ m}$

$t = 2.5 \text{ sec}$ $f = 0.4$

$$C = \frac{1000v}{s}$$

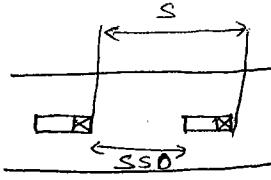
$$s = SSD + L$$

$$= (0.278 vt + \frac{v^2}{254f}) + L$$

$$= 45.175 + 41.58 + 5$$

$$= 91.75$$

$$C = \frac{1000 \times 65}{91.75} = 708.37 \text{ PCU/hr/lane.}$$



Basic capacity (or) theoretical capacity:-

The maximum no. of vehicles that can pass out at a given section of road during one hour under ideal road was condition and traffic condition.

$$C = \frac{1000v}{s}$$

v = speed of 'v' in kmph

s = space head way in 'm'.

$$s = SSD + L$$

$$= (\text{lay distance}) + (\text{Length of } v) L$$

$$= 0.287vt + L$$

$$t = \frac{\text{total}}{\text{time reaction of driver}}$$

The total reaction time of the driver is 0.7 sec.

Ex:-) The theoretical capacity of a traffic lane with a speed at 40 kmph and avg. length of the vehicle 5m is

A) $v = 40 \text{ kmph}$

$$t = 0.7 \text{ sec}$$

$$L = 5 \text{ m}$$

$$s = SSD + L$$

$$= LD + L$$

$$= (0.278 \times 40 \times 0.7) + 5$$

$$s = 12.784$$

$$C = \frac{1000 \times 40}{12.784} = 3128.9 \text{ PCU/hr/lane}$$

P.g No:- 70

1. $s = 30 \text{ m}$

$$v = 60 \text{ kmph}$$

$$C = \frac{1000v}{s} = \frac{1000 \times 60}{30} = 2000 \text{ PCU/hr/lane.}$$

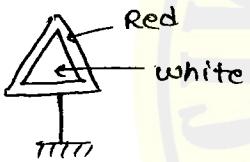
TRAFFIC SIGNS

According to Indian motor vehicle act traffic signs are divided into 3 categories.

1. Regulatory (or) Mandatory signs:-

1. straight movement of traffic is prohibited 
2. one way traffic
3. Right turn is prohibited 
4. U-turn not allowed 
5. NO parking 
6. speed limit 
7. Over taking is prohibited 

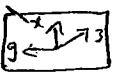
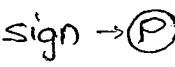
2. Warning signs or cautionary signs:-



- Right turn is allowed
- Hair pin bend / sharp curve
- Reverse curve
- T T - intersection
-][Narrow bridge

3. Informatory signs:-

The signs which under comes under this category

- 1) Direction and place identification sign 
- 2) Facility information sign such as hospital, school, parking sign → 

Traffic characteristics:-

1. Road user (Driver, pedestrian)
2. vehicular
 - static characteristics (L, W, H)
 - dynamic characteristics (+, - velocity acceleration).

Maximum dimensions of the vehicles according to IRC :-

(11)

1. Width of the vehicle maximum is 2.5 m
2. Height → a) single deck → 3.8 m
b) Double deck → 4.75 m
3. Length of the vehicle for a) single unit truck → 11 m
b) single unit bus → 12 m
c) Tractor → 16 m
d) Trailer / Tractor → 18 m

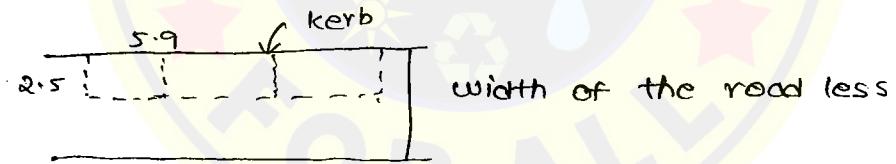
Parking studies :-

There are two types of parking systems.

1. On street parking / kerb parking (divider between foot path and carriage way)
2. Off - street parking

On street parking :-

1. Parallel parking :-

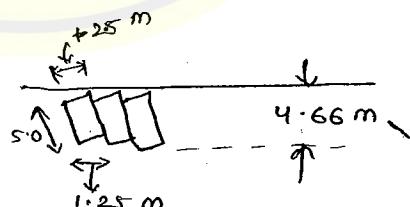


$$N = \frac{L}{5.9}$$

2. Angular parking :-

30° angular parking

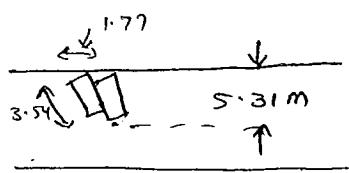
$$N = \frac{L - 1.25}{5}$$



$N = \text{No. of parking lots}$

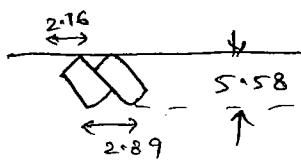
45° angular parking

$$N = \frac{L - 1.77}{3.54}$$

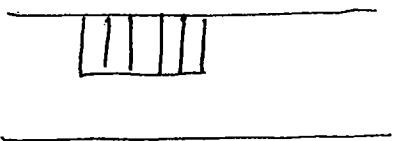


60° angular parking

$$N = \frac{L - 2.16}{2.89}$$



90° angular parking



$$N = \frac{L}{2.5}$$

Off street parking:-

the various types of parkings are

1. surface parking
2. Multi storey parking
3. Roof parking
4. Mechanical parking
5. Under ground parking.

Parking Index:-

percentage of available no. of parking base with
respective no. of base available.

$$= \frac{\text{No. of base occupied}}{\text{No. of base available}}$$

Parking turnover :-

The rate of usage of available parking space

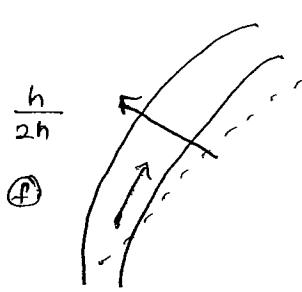
Ex:- 100 parking lots

If there are 100 parking spaces used by thousand
vehicles, in a period of 12 hours then parking turnover
is equal to $\frac{1000}{100} = 10 \text{ veh/parking space for a period}$

of 12 hours.

Accident:

1. Road user (Driver, pedestrian)
2. Vehicle
3. Road characteristics
4. Environmental conditions



⇒ the frequency of accident occurring at same place that place are called Black spots.

(12)

Black spot:-

Three or more accidents occurring at the same place in a year is known as Black spot.

Objectives of Accident studies:-

1. To identify high accident locations for detailed study
2. To improve general geometric design standards in relation to accidents.
3. To workout financial losses in accidents.
4. To evaluate safety programs
5. To planning the data and enforcement actions
6. To furnish the data for planning of education and enforcement actions.

Collision diagram:-

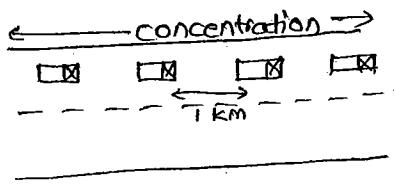
1. It shows the approximate path of vehicles and pedestrians involved in the accidents.
2. The symbols used are "→" motor vehicle moving in forward direction. "←" then motor vehicle moving in reverse direction. "→→" then pedestrian, "□ - parked vehicle", □ - Fixed object, → over taking, ↗ out of control, →•← fatal accident (or) death accident, →○← person injury.

of highway :-
Accident control measures:- verification of geometric design feature

1. Engineering
2. Enforcement
3. Education
4. Concentration (ideas)

Concentration:-

concentration it is also called density.



the no. of vehicles in present in 1 km length of the road.



Alignment :-

Layout of the centre line of the highway on the ground. There are the two types of Alignment.

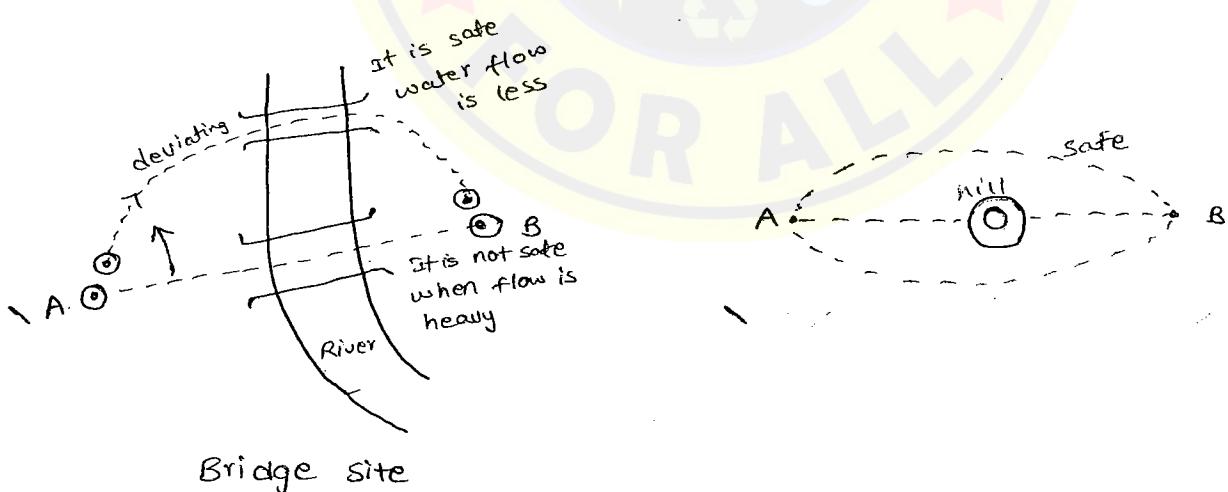
- Horizontal Alignment
- Vertical Alignment

Basic requirements of Alignment:-

- short
- Easy
- safe
- Economy

Obligatory points:-

- Main control points to controlling the Alignment
- Obligatory points where the Alignment is passing
Ex:- Bridge site, Mountains or hills, Intermediate town

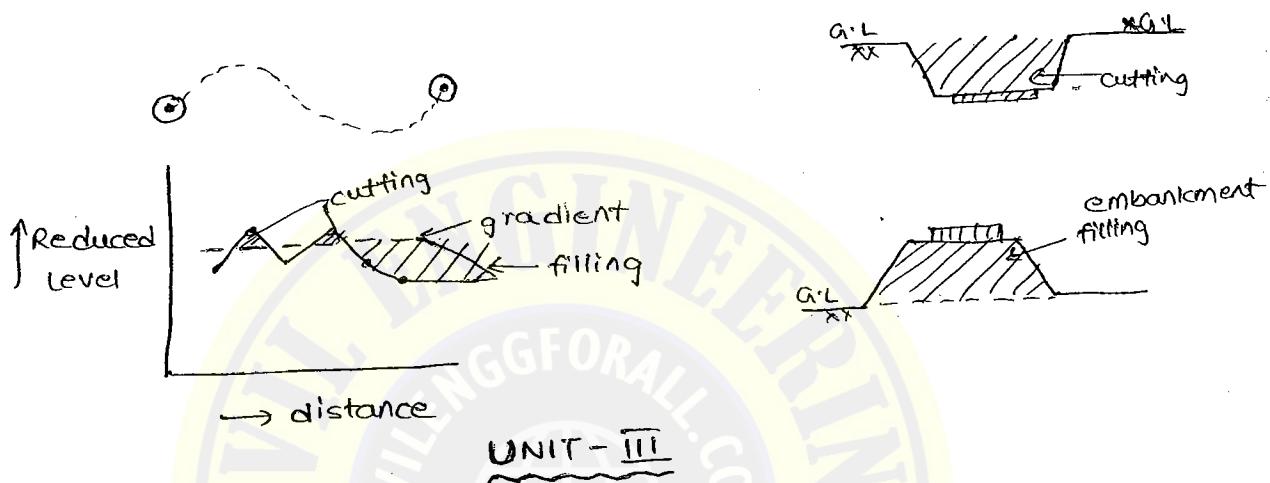


- Where the alignment should not pass.
Ex:- Religious places, Grave yards

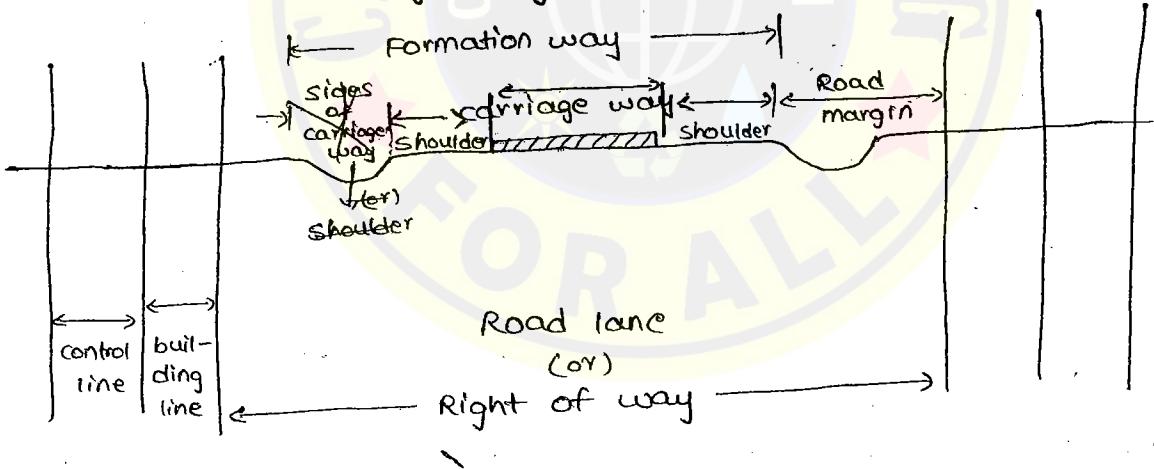
Engineering surveys :-

The four stages of engineering surveys are

1. Map study → rough guidance of alternate alignments
2. Reconnaissance survey → select the possible alternate alignment
3. Preliminary survey → select the most suitable alignment
4. Final location and detailed study → preparation of longitudinal section and cross section for the selected Alignment.



Cross section of Highway :-



The surface characteristics of the pavement are

1. Friction
2. Undulation
3. cross slope (or) camber

Friction:-

Friction is developed between wheels of the vehicles and pavement surface. Ex:- Skid
Slip

Skid:-

The longitudinal movement of vehicle is more than the rotational movement of wheels of vehicle.

Slip:-

The rotational movement of wheels of vehicle is more than the longitudinal movement of vehicle.

Observation:-

1. It is considered in terms of longitudinal coefficient of friction (f_l) in stopping side distance (SSD). It ranges from 0.35 to 0.40
2. It is also considered in terms of lateral coefficient of friction in super elevation. It is denoted with ' e '. This value is equal to 0.15

2. Undulation (or) unevenness:-

1. Cumulative vertical undulations of the pavement surface per unit length of the road.



It is expressed (cm/km)

IRC given some undulations:-

1. upto 150 cm/km → good pavement
2. upto 250 cm/km → satisfactory
3. Greater 300 cm/km → uncomfortable
2. The instrument used for measurement of unevenness (or) bump indicator and unevenness indicator.
3. Camber (or) cross slope:-

1. The slopes provided in transverse direction of pavement to drain off rain water from the pavement surface to the sides.

a. parabolic camber :-

consider the parabolic equation

$$y = \frac{x^2}{a}$$

where, $a = \text{constant}$ which is equal to $\frac{nw}{2}$

$$\therefore a = \frac{nw}{2}$$

$$y = \frac{2x^2}{nw}$$

where, $n = \text{Rate of camber}$

$w = \text{width of the road}$

$x = \text{distance from middle section of the road to the side.}$

$$x_1 = \frac{w}{8} \Rightarrow y_1$$

$$x_2 = \frac{2w}{8} \Rightarrow y_2$$

$$x_3 = \frac{3w}{8} \Rightarrow y_3$$

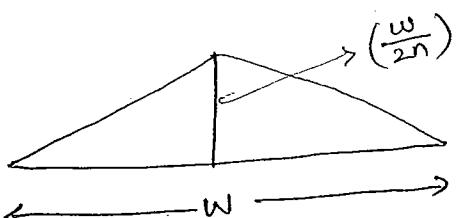
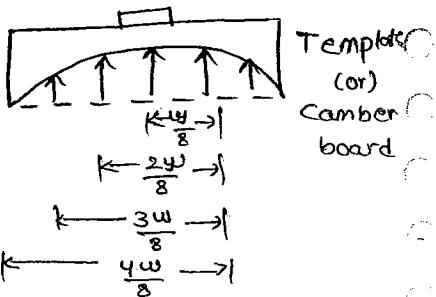
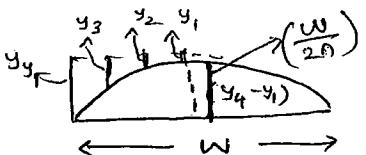
$$x_4 = \frac{4w}{8} \Rightarrow y_4$$

Note:-

Height of the crown (or) Height of the middle section of pavement is equal to $\frac{nw}{8}$ ($\frac{w}{2n}$).

i. It is comfortable for fast moving vehicles.

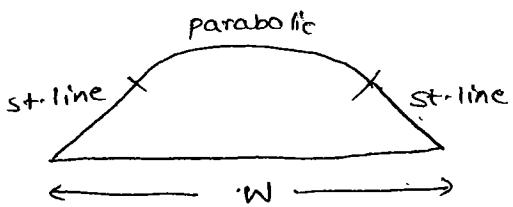
b. straight line camber:-



i. It is comfortable for slow moving vehicles.

c. combination of both parabolic and straight line:

(15)



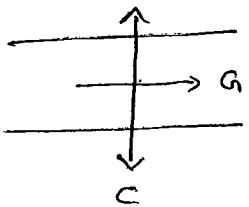
It is comfortable for both slow moving vehicles and fast moving vehicles.

Standard values of camber as recommended by IRC:-

S.NO.	pavement surface	Rainfall	
		Heavy	Light
1.	Cement concrete high bituminous pavement	1 in 50 (2%)	1 in 60 (1.7%)
2.	Thin bituminous surface	1 in 40	1 in 50
3.	W.B.M Road (combination of Aggregate and soil)	1 in 33	1 in 40
4.	Village road (or) earthen road	1 in 25	1 in 33

1. The amount of camber depends on type of pavement surface and intensity of rainfall.
2. Flatter cambers are provided for high quality of pavement surface.
 w = width of the road
3. width of single traffic lane is 3.75 m (or) 3.8 m
4. width of two lane road is 7 m. width of two lane with Curb Kerb is 7.5 m
5. Additional lane increase the pavement by 3.5 m
6. width of three lanes = $7 + 2(3.5) = 10.5$ m
7. width of four lane = $7 + 2(3.5) = 14$ m
8. width of intermediate lane is 5.5 m

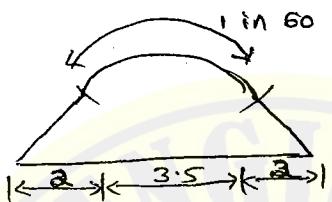
Q. For better drainage and smooth flow of traffic and camber of the road should be equal to half of the longitudinal gradient.



$$C = \frac{1}{2} G$$

$$2C = G$$

Ex:-) A road camber is given in the following figure the equation used for design is



A) $y = \frac{2x^2}{nw}$

$$n = 60 \quad w = 2 + 2 + 3.5 = 7.5 \text{ m}$$

$$y = \frac{2 \times x^2}{60 \times 7.5}$$

$$y = \frac{x^2}{225}$$

Ex:-)

List - I

- A. WBM
- B. Bituminous
- C. Rigid pavements (CC)
- D. Earth

List - II

- 1. 1 in 72
- 2. 1 in 60
- 3. 1 in 48
- 4. 1 in 25

A) D - 4, C - 1, B - 2, A - 3

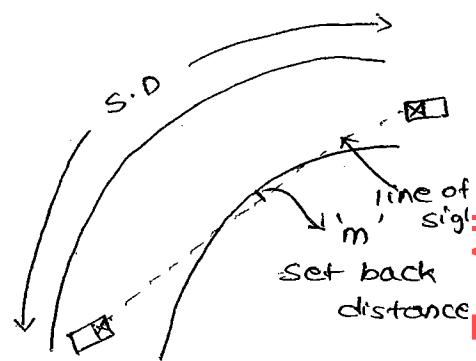
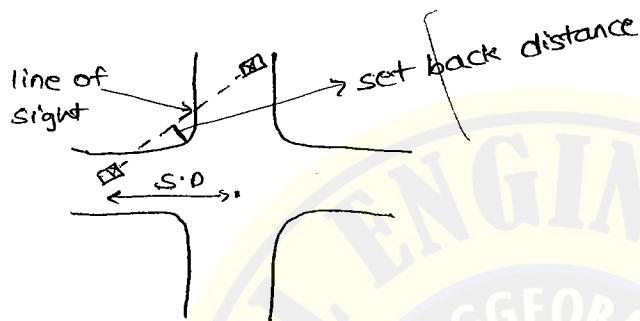
Ex:-) A straight line camber for cement concrete road for areas of light rainfall width of the road 3.5m calculate the height of the ground & crown?

$$\begin{aligned}
 A) \quad & \frac{W}{2n} \quad 1 \text{ in } 60 \\
 & n = 60 \\
 & = \frac{3.5}{2 \times 60} \\
 & = \frac{3.5 \times 100 \times 10}{2 \times 60} \\
 & = 29.2 \text{ mm}
 \end{aligned}$$

UNIT - V

Sight Distance:-

consider a horizontal curve, a cross intersection



Sight side distance situations are consider in three ways:-

1. Stopping sight distance (SSD)
2. Over taking sight distance (OSD)
3. Intermediate sight distance (ISO)

Stopping sight distance:-

(or) Non passing sight distance

1. The length of the road required to stop the vehicle without any accident.
2. At verticle summit curve the height of high level of driver 1.2m and height of object 0.15m above the road surface then the distance b/w these two is stopping sight distance.

$$\text{SSD} = \text{lag distance} + \text{breaking distance},$$

Lag distance → Distance travelled by the vehicle total reaction time of driver.

breaking distance \rightarrow distance travelled by the vehicle after the application of brakes

$$SSD = vt + \frac{v^2}{2g(f \pm 0.01n)}$$

v = speed of vehicle 'm/sec'

t = total reaction time of driver in sec.

g = Acceleration due to gravity

f = longitudinal coefficient of friction = 0.35 to 0.4 based on vehicle

n = slope of the road = gradient in %

$$SSD = 0.278 vt + \frac{v^2}{254(f \pm 0.01n)} \quad (\text{use only inclined surface})$$

Use '+' sign for ascending gradient and '-ve' sign for descending gradient

\Rightarrow If vehicle is moving on leveled surface

$$S.S.D = 0.278 vt + \frac{v^2}{254f}$$

Break efficiency :- (n) :-

$$S.S.D = 0.278 vt + \frac{v^2}{254(fn)}$$

- \Rightarrow Minimum stopping sight distance = $\frac{\text{stopping sight distance}}{\text{calculated for one way traffic lanes}}$
- \Rightarrow Minimum SSD = SSD calculated for two or more lanes with two way traffic.
- \Rightarrow Minimum SSD = $2 \times$ SSD calculated for single lane two way traffic
- \Rightarrow The deceleration, retardation in the process of breaking dist. is given as $a = fg$

a = retardation (or) deceleration

g = acceleration due to gravity.

- ⇒ Total reaction time of the driver includes perception time and break reaction time.
- ⇒ Based on PIEV (perception Intellectual Emotion violation) under normal conditions. The total reaction time of the driver is 2.5 sec

Ex:- P.g No:- 18

$$1. \text{ Breaking distance} = 76.5 \text{ m}$$

$$v = 80 \text{ kmph}$$

$$\text{Breaking distance} = \frac{v^2}{254f}$$

$$76.5 = \frac{80^2}{254 f}$$

$$f = 0.33$$

$$2. \quad v = 50 \text{ kmph}$$

$$f = 0.37$$

$$t = 2.5 \text{ sec}$$

$$\begin{aligned} S.S.D.B.D &= 0.278 vt + \frac{v^2}{254f} \\ &= 0.278 (50) (2.5) + \frac{(50)^2}{254 (0.37)} \\ &= 61.34 \text{ m} \end{aligned}$$

$$3. \quad v = 80 \text{ kmph} ; \quad t = 3 \text{ sec} ; \quad f = 0.5$$

$$SSD = 0.278 t + \frac{v^2}{254f}$$

$$SSD = 117.11 \text{ m.}$$

$$4. \quad v = 60 \text{ kmph} ; \quad f = 0.4 ; \quad t = 3 \text{ sec}$$

$$SSD = 0.278 \times 60 \times 3 + \frac{60^2}{254 \times 0.4}$$

$$SSD = 85.47 \text{ m}$$

For two lane two way traffic = 85.47 m

But for single lane two way traffic min. SSD = 2×85.47
= 171 m.

6. $v = 80 \text{ kmph}$, $t = 2.5 \text{ sec}$; $f = 0.4$

$$\text{SSD} = 0.278 \times 80 \times 2.5 + \frac{80^2}{254(0.4)}$$
$$= 55.6 + 62.9 \Rightarrow 118.6$$

9. $v = 80 \text{ kmph}$, $t = 2 \text{ sec}$, $f = 0.4$, $n = 5\%$. (falling gradient)

$$\text{SSD} = 0.278 vt + \frac{v^2}{254(f - 0.01n)}$$
$$= 0.278 \times 80 \times 2 + \frac{80^2}{254(0.4 - 0.01 \times 5)}$$

$$\text{SSD} = 116.47 \text{ m}$$

12. $f = 0.4$, $a = fg$, $g = 9.81 \text{ m/sec}^2$

$$a = 0.4 \times 9.81$$
$$= 3.92 \text{ m/s}^2$$

14. $v = 72 \text{ kmph}$, $n = 2\% \uparrow$, $t = 1.5 \text{ sec}$, $f = 0.15$

$$\text{SSD} = 0.278 \times 72 \times 1.5 + \frac{72^2}{254(0.15 + 0.01 \times 2)}$$
$$= 150 \text{ m}$$

18. $v = 80 \text{ kmph}$; $n = 2\% \downarrow$ $t = 2.5 \text{ sec}$ (assume) $f = 0.35$ (\because table)

$$\text{SSD} = 0.278 \times 80 \times 2.5 + \frac{80^2}{254(0.35 - 0.01 \times 2)}$$
$$= 132 \text{ m}$$

$v (\text{kmph})$	20-30	40	50	60	65	80	100
f	0.4	0.38	0.37	0.36	0.36	0.35	0.35

Overtaking sight distance (or) safe passage sight distance :-

To overtake slow moving vehicle with respect to opposite coming vehicle the length of the road required is the overtaking sight distance. (or)

At verticle summit curve the height of eye level of driver and height of object is 1.2m above the road surface then the distance b/w these two is overtaking sight distance

A = fast moving vehicle

A = overtaking vehicle

B = slow moving vehicle

i.e., overtaken vehicle

C = opposite coming vehicle

$$OSD = d_1 + d_2 + d_3$$

d_1 = distance travelled during total reaction time of the driver

d_2 = distance travelled by the vehicle during overtaking process.

d_3 = distance travelled by opposite coming vehicle.

$$OSD = v_b t + (v_b T + 2s) + vt$$

v_b = speed of slow moving vehicle in m/s

t = total reaction time of the driver

T = Time taken for overtaken process

s = spacing b/w two vehicles

v = speed of fast moving vehicle in m/s

$$s = 0.7 v_b t + l$$

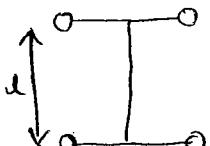
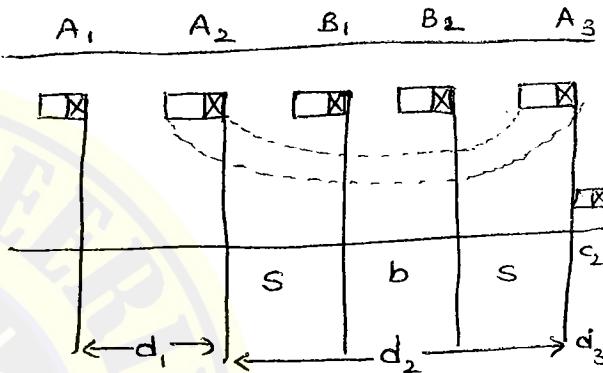
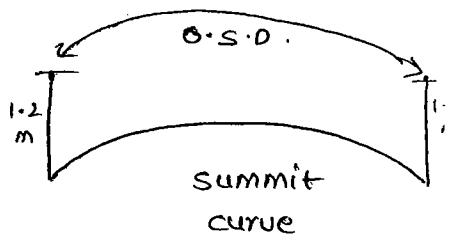
l = length wheel base of vehicle

$$T = \sqrt{\frac{4s}{a}}$$

T in sec

a = acceleration of fast moving vehicle in

m/sec^2 .



$$OSD = (0.278 v_b t) + [(0.278 v_b T) + 2S] + (0.278 UT)$$

$$S = 0.2 v_b t$$

For $v = \text{kmph}$

v_b $T = \text{sec}$

$S = \text{m}$

$$T = \sqrt{\frac{14.4 S}{A}} \leftarrow \text{if 'A' is in km/hr/sec}$$

(use this)

$A = \text{km/hr/sec}$

$v_b = \text{slow moving vehicle}$

$v = \text{fast moving vehicle}$

v_b in kmph λ in 'm'.

Assumptions:-

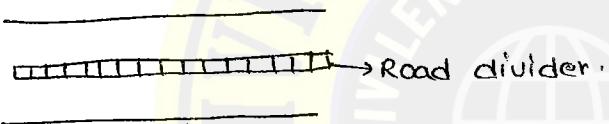
In problems design speed is given only, then

(i) $v = \text{design speed}$ and $v_b = (v - 16) \text{ kmph}$

(ii) $t = 2 \text{ sec}$

(iii) OSD for divided highway $OSD = d_1 + d_2$ only

$$OSD = (0.278 v_b t) + (0.278 v_b T + 2S)$$



(iv) For one way traffic lanes

$$OSD = d_1 + d_2 \text{ only}$$

Overtaking zone:-

Min length of overtaking zone is equal to 3 times of OSD

→ Desirable length of overtaking zone = 5 times OSD.

P.g NO:- 21

$$4. S = 30 \text{ m} ; a = 1.3 \text{ m/sec}^2$$

$$T = \sqrt{\frac{4S}{a}} = \sqrt{\frac{4 \times 30}{1.3}}$$

$$T = 9.6 \text{ sec.}$$

2. The speeds of overtaking and overtaken vehicles are 80 kmph and 50 kmph respectively. The acceleration of overtaking vehicle is 2.5 kmph/sec spacing b/w the vehicle is 16 m Reaction time of driver 2 sec. calculate the OSD for one way traffic road? (19)

A. $v = 80 \text{ kmph}$ $v_b = 50 \text{ kmph}$, $a = 2.5 \text{ kmph/sec}$, $t = 2 \text{ sec}$, $s = 16$

$$T = \sqrt{\frac{14.4s}{A}}$$

$$= \sqrt{\frac{14.4 \times 16}{2.5}}$$

$$T = 9.6 \text{ sec}$$

Complete Class Note Solutions
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$$\begin{aligned} \text{OSD} &= (0.278 v_b t) + (0.278 v_b T + 2s) \\ &= (0.278 \times 50 \times 2) + (0.278 \times 50 \times 9.6) + 2 \times 16 \end{aligned}$$

$$\text{OSD} = 193.24 \text{ m for one way traffic.}$$

3. calculate the overtaking sight distance for two way traffic

A. $d_3 = 0.278 VT$
 $= 0.278 \times 80 \times 9.6$
 $= 213.5$

$$\begin{aligned} \text{OSD} &= 193.24 + 213.5 \\ &= 406.74 \text{ m.} \end{aligned}$$

Intermediate sight distance (I.S.D):-

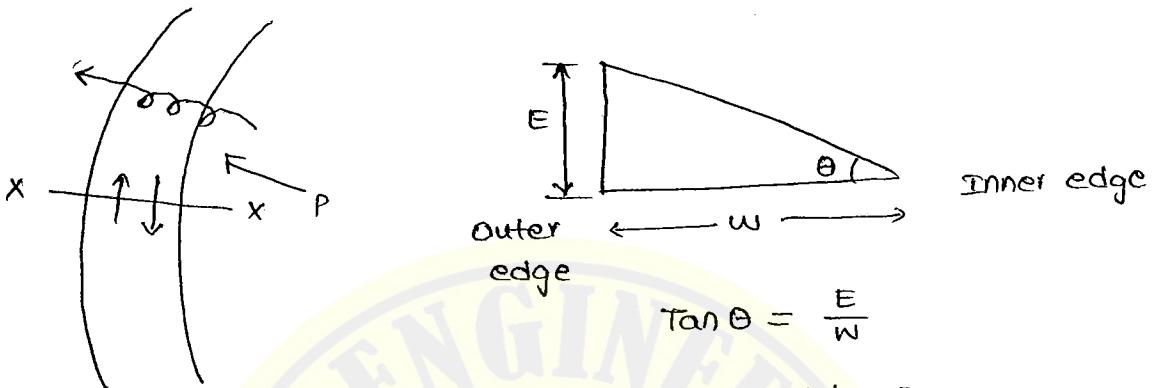
When ever it is not possible to provide the required overtaking sight distance (OSD) then consider intermediate sight distance (ISD) which is equal to 2 times of OSD

$$\boxed{\text{ISD} = 2 \text{ OSD}}$$

Horizontal Curves

Super Elevation :-

Raising of outer edge of pavement with respect to inner edge along the width of the road on horizontal curve is known as Super Elevation.



$$\tan \theta = \frac{E}{w}$$

$$E = w \tan \theta$$

$$E = we$$

E = Height at the outer edge of the pavement

e = Amount of Super elevation
(or)

Rate of super elevation.

w = Width of super e the road

The basic equation of super elevation is $e+f = \frac{v^2}{gR}$

f = lateral coefficient of friction

$f = 0.15$

v = speed of the vehicle in m/sec

g = Acceleration due to gravity

R = Radius of curve in m.

$$e+f = \frac{v^2}{127 R}$$

v = kmph

R = 'm'

(i) Max value of super elevation

(20)

a. $e_{max} = 7\% = 0.07$ — For plane terrain

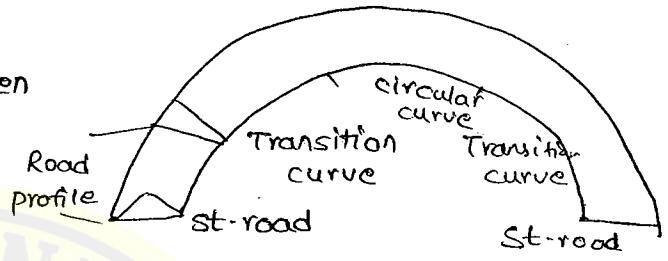
b. $e_{max} = 10\% = 0.10$ — For Mountainous

(ii) Min. super elevation:

If calculated super elevation is less than or equal to camber of road surface then the min. super elevation is equal to camber of road surface.

If $e_{cal} < \text{camber}$ then

$$e_{min} = \text{camber}$$



(iii) Equilibrium super elevation:-

The pressure on inner wheels and outer wheels is equal then substitute lateral coefficient of friction (f) = 0

$$e_{equilibrium} = \frac{v^2}{127R}$$

(iv) Super elevation for mixed traffic -

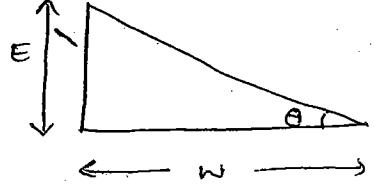
a. consider 75% of design speed

b. substitute lateral coefficient of friction (f) = 0

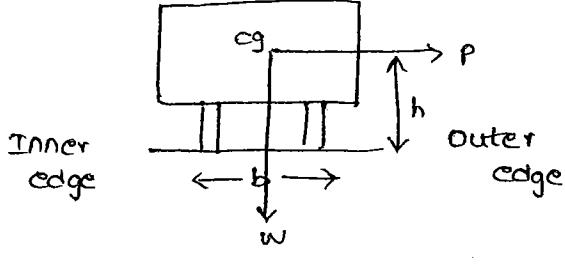
$$e = \frac{(0.75v)^2}{127R}$$

(or)

$$e = \frac{v^2}{225R}$$



consider without Super elevation



$$\tan \theta = e$$

$$\tan \theta = \frac{E}{w}$$

$$E = w \tan \theta$$

$$E = \sigma w$$

$$P = \frac{w v^2}{g R}$$

P = centrifugal force

w = weight of vehicle

h = height of C.G. of vehicle above road surface.

b = width of wheel base of vehicle.

i. There is danger of over turning when centrifugal ratio $\frac{P}{w}$ or v^2/gr is equal to $b/2h$.

2. There is a danger of lateral skidding if centrifugal ratio

$\frac{P}{w}$ or $\frac{v^2}{gr}$ = Lateral coefficient of friction.

3. The vehicle takes place lateral skidding with out over turning if the value of lateral coefficient of friction (f) is less than $b/2h$.

4. The vehicle takes place over turning before skidding if the value of $b/2h <$ than lateral coefficient of friction(f).

Design of super elevation:-

i. Consider 75% of design speed by neglecting lateral coefficient of friction then calculate super elevation.

$$e+f = \frac{v^2}{127R} \Rightarrow e+0 = \frac{(0.75v)^2}{127R}$$

$$e_{cal} = \frac{v^2}{225R}$$

2. compare calculated super elevation with design values of super elevation.

3. If $e_{cal} > e_{max}$ then super elevation is restrict to maximum super elevation.

4. If $e_{cal} < e_{max}$ the super elevation is restrict to calculated super elevation.

5. Calculate lateral coefficient of friction for design value of super elevation.

$$f_{cal} = f = \frac{v^2}{127R} - e_{max}$$

6. compare $f_{cal} < 0.15$ the design speed is suitable for super elevation.
7. If $f_{cal} > 0.15$ then calculate restricted speed (or) allowable speed (or) permissible speed.
8. calculate allowable speed by considering design values of super elevation and lateral coefficient of friction.

$$V = \sqrt{127 R (e+f)}$$

P.g NO:- 24

$$3. e+f = \frac{v^2}{127 R}$$

$$e_{equ} + 0 = \frac{50^2}{127 \times 100}$$

$$e_{equ} = 0.196$$

$$6. e + 0.15 = \frac{60^2}{127 \times 128}$$

$$e = 0.0714$$

$$= 7.14\%$$

$$4. e+f = \frac{v^2}{127 R}$$

$$e + 0.15 = \frac{60^2}{127 \times 150}$$

$$e = 0.038 \\ = 3.8\%$$

$$8. e+f = \frac{v^2}{127 R} \text{ but for mixed traffic}$$

$$e_{mix} = \frac{(0.75 v)^2}{127 R} - 0$$

$$e_{mix} = 0.154$$

15. Without superelevation

$$e+f = \frac{v^2}{9R}$$

$$f = 0.1 \text{ and } e = 0$$

$$0+0.1 = \frac{v^2}{9.81 \times 98}$$

$$v^2 = 96.138$$

$$v = 9.8 \text{ m/sec}$$

17. $b = 2.4 \text{ m}, h = 4.2 \text{ m}; f = 0.11$

$$\frac{b}{2h} = \frac{2.4}{2 \times 4.2}$$

$$= 0.286$$

$f < \frac{b}{2h}$ therefore lateral

skidding occur first.

$$19. r = 100 \text{ m} ; v = 50 \text{ kmph}$$

$$f = 0.15$$

$$e+f = \frac{v^2}{127 R}$$

$$e = \frac{50^2}{127 \times 100} - 0.15$$

$$e = 0.047$$

$$e = 1 \text{ in } 21.3$$

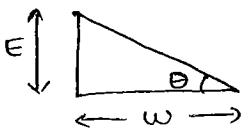
$$20. r = 200 \text{ m}, f = 0.15, v = 40 \text{ kmph}$$

$$e_{\text{equal}} + o = \frac{40^2}{127 \times 200}$$

$$e_{\text{equ}} = 0.063$$

$$= 6.3\%$$

$$21. \text{ For mixed } e+o = \frac{(0.75v)^2}{127 R}$$



$$e = \frac{(0.75 \times 80)^2}{127 \times 480}$$

$$e = 0.059$$

$$E = e \omega$$

$$= 0.059 \times 7.5$$

$$E = 0.4425 \text{ m}$$

Design speed :-

Classification of

Highway

	Plain Terrain		Mountainous terrain	
	Ruling (v)	Minimum (v')	Ruling (v)	Minimum (v')
NH & SH	100	80	50	40
M.D.R	80	65	40	30
ODR	65	50	30	25
VR	50	40	25	20

1. Calculate ruling, minimum radius by considering ruling design speed (v) by using basic equation of super elevation.

$$e+f = \frac{v^2}{127 R}$$

$$R_{\text{ruling}} = \frac{v^2}{127(e+f)}$$

2. calculate absolute min radius of considering min design speed (v') by using basic equation of super elevation.

$$R_{ab} \cdot \min = \frac{v^2}{127(e+f)}$$

P.9 NO. 24

$$\begin{aligned} 7. R_{ruling} &= \frac{v^2}{127(e+f)} \\ &= \frac{100^2}{127(0.07+0.15)} \end{aligned}$$

$$R_{rul} = 357.9 \text{ m}$$

$$\begin{aligned} 12. R_{abs} &= \frac{v^2}{127(e+f)} \\ &= \frac{80^2}{127(0.07+0.15)} \end{aligned}$$

$$R_{abs} = 229.06 \text{ m}$$

$$13. v = 100 \text{ kmph}, e = 0.10, f = 0.15$$

$$\begin{aligned} R_{ruling \cdot \min} &= \frac{100^2}{127(0.1+0.15)} \\ &= 314.9 \text{ m} \end{aligned}$$

$$25. v = 100 \text{ kmph}, e = 0.08, f = 0.12$$

$$\begin{aligned} R_{abs} &= \frac{100^2}{127(0.08+0.12)} \\ &= 393.7 \text{ m} \end{aligned}$$

$$26. \text{ For NH on plain terrain design speed} = 80 \text{ kmph}$$

$$e = 0.07$$

$$R_{\min} = \frac{80^2}{127(0.07+0.15)} = 229.06 \text{ m}$$

$$R_{\min} = \frac{100^2}{127(0.07+0.15)} = 357.9 \text{ m}$$

Take higher for
min. radius.

$$28. R = \frac{100^2}{127(0.07+0.15)}$$

$$R = 357 \text{ m}$$

$$22. c+f = \frac{v^2}{127 R}$$

$$f = \frac{100^2}{127 \times 400} - 0.07$$

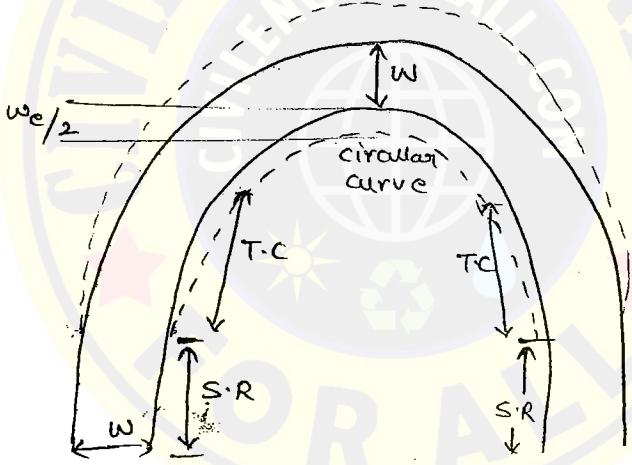
$$f = 0.126$$

$$f \approx 0.13$$

UNIT - VIII

Extra width of pavement (w_e):-

consider entire horizontal curve which consists of straight road, transition curve and circular curve.



w_e = mechanical widening of pavement + psychological widening of pavement.

$$w_e = w_m + w_{ps}$$

w_m = Mechanical widening is provided to overcome the off tracking of a vehicle.

The path tracked by front wheels of vehicle does not match with path tracked by back wheels of vehicle. This is known as off-tracking.

$$R_{ab} \cdot \min = \frac{v^2}{127(e+f)}$$

P-9 NO. 24

$$\begin{aligned} 7. R_{ruling} &= \frac{v^2}{127(e+f)} \\ &= \frac{100^2}{127(0.07+0.15)} \end{aligned}$$

$$R_{rul} = 357.9 \text{ m}$$

$$\begin{aligned} 12. R_{abs} &= \frac{v^2}{127(e+f)} \\ &= \frac{80^2}{127(0.07+0.15)} \end{aligned}$$

$$R_{abs} = 229.06 \text{ m}$$

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$$25. v = 100 \text{ kmph}, e = 0.08, f = 0.12$$

$$\begin{aligned} R_{abs} &= \frac{100^2}{127(0.08+0.12)} \\ &= 393.7 \text{ m} \end{aligned}$$

26. For NH on plain terrain design speed = 80 kmph

$$e = 0.07$$

$$R_{\min} = \frac{80^2}{127(0.07+0.15)} = 229.06 \text{ m}$$

$$R_{\min} = \frac{100^2}{127(0.07+0.15)} = 357.9 \text{ m}$$

Take higher for
min. radius.

$$Q8. R = \frac{100^2}{127(0.07+0.15)}$$

$$R = 357 \text{ m}$$

$$Q2. c+f = \frac{v^2}{127 R}$$

$$f = \frac{100^2}{127 \times 400} - 0.07$$

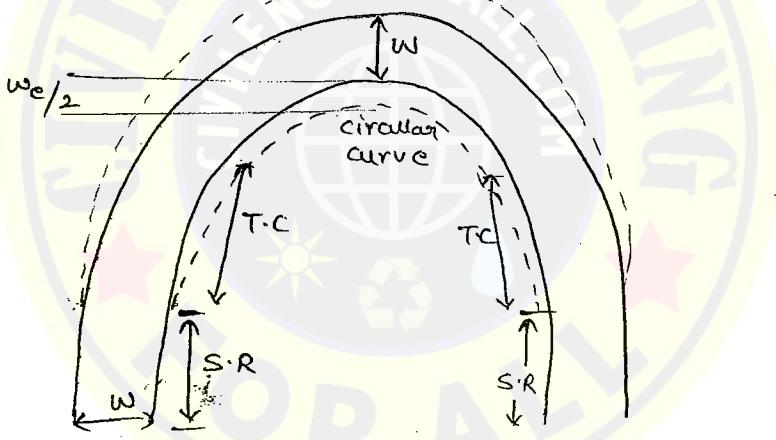
$$f = 0.126$$

$$f \approx 0.13$$

UNIT - VIII

Extra width of pavement (w_e):-

consider entire horizontal curve which consists of straight road, transition curve and circular curve.



w_e = mechanical widening of pavement + psychological widening of pavement

$$w_e = w_m + w_{ps}$$

w_m = Mechanical widening is provided to overcome the off tracking of a vehicle.

The path tracked by front wheels of vehicle does not match with path tracked by back wheels of vehicle. This is known as off-tracking.

$$w_e = w_m + w_{ps}$$

$$w_e = \frac{nl^2}{2R} + \frac{v}{9.5\sqrt{R}}$$

where

n = no. of traffic lanes

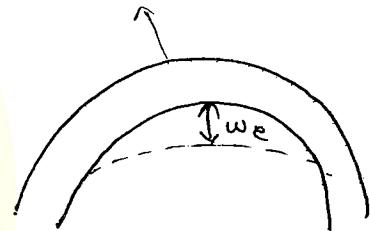
l = length of wheel base of vehicle

R = Radius of curve in 'm'

v = speed of vehicle in kmph.

For extra width = 14 m, $n = \frac{14}{3.5} = 4$ No's.

i) If radius of curve are less than 50 m, then extra width of pavement is provided inside of the curve.



ii) If radii of curve is greater than or equal to 50 m then extra width is equally distributed on both sides of the curve.

iii) The mechanical widening $\frac{l^2}{2R}$ is provided for one vehicle along one traffic lane on Horizontal curve.

iv) The mechanical widening $\frac{nl^2}{2R}$ is required for ' n ' no. of vehicles along ' n ' no. of traffic lanes on horizontal curve.

P.g NO:- 28

$$\begin{aligned} 1. \quad w_m &= \frac{nl^2}{2R} \\ &= \frac{1 \times 6.5^2}{2 \times 125} \end{aligned}$$

$$w_m = 0.169$$

$$\begin{aligned} 2. \quad w_e &= \frac{nl^2}{2R} + \frac{v}{9.5\sqrt{R}} \\ &= \frac{2 \times 6.5^2}{2 \times 150} + \frac{60}{9.5\sqrt{150}} \end{aligned}$$

$$w_e = 0.755 \text{ m}$$

$$3. \omega_e = \frac{n\alpha^2}{2R} + \frac{v}{9.5\sqrt{R}}$$

$$= \frac{2 \times 6^2}{2 \times 400} + \frac{100}{9.5\sqrt{400}}$$

$$= 0.616 \text{ m}$$

$$4. \omega_m = \frac{n\alpha^2}{2R}$$

$$= \frac{n(2\alpha)^2}{2 \times R}$$

$$\omega_m = 4 \left(\frac{n\alpha^2}{2R} \right)$$

\Rightarrow 4 times

$$5. n = 300 \text{ m}, \alpha = 6.1 \text{ m}, v = 80 \text{ kmph}$$

$$\omega_e = \frac{2 \times 6.1^2}{2 \times 300} + \frac{80}{9.5\sqrt{300}}$$

$$= 0.124 + 0.486$$

$$= 0.61 \text{ m}$$

$$7. \omega_{ps} = \frac{v}{9.5\sqrt{R}} = \frac{95}{9.5\sqrt{100}} = 1.0 \text{ m}$$

UNIT - X

Transition curve:-

A transition curve is introduced b/w a straight road and a circular curve. The radius of transition curve is infinity at the end of straight road and min. at the starting of circular curve.

Types:-

- 1. spiral curve 2. Lemniscate curve 3. cubic parabola.

- i) spiral is the best transition curve as IRC recommended.
- ii) In spiral curve radius is inversely proportional to length of curve and rate of change of centrifugal acceleration is uniform through out the length of the curve. (c in m^3/s^3)
- iii) All the three follow the same path upto the deflection angle 4° .

* Length of transition curve :-

(i) Length of the transition curve, $L = \frac{v^3}{CR} \rightarrow \text{m/sec}$ (24)

R = Radius of the curve in 'm'.

C = Rate of change of centrifugal acceleration.

$$C = \frac{80}{75+v} \rightarrow \text{kmph}$$

v = Speed of the vehicle in kmph

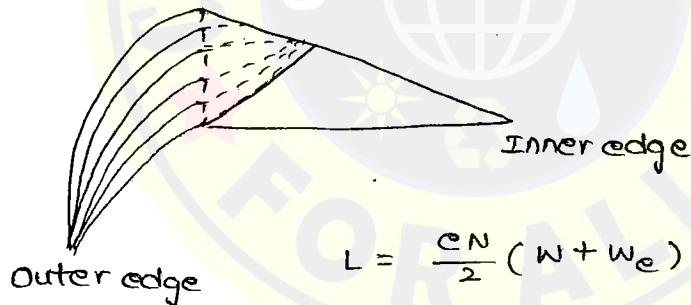
Generally 'c' value lies between 0.5 to 0.8

$$L = \frac{0.0215 v^3}{C R \rightarrow \text{m}} \rightarrow \text{kmph}$$

\downarrow
 m/sec^3

i) By considering rate of introduction of super elevation (N):

- By changing camber shape to \neq super elevation there are two types
- a. pavement is rotated about centre line.



$$L = \frac{CN}{2} (W + W_e)$$

Outer edge of the pavement shifting

where, e = rate of super elevation

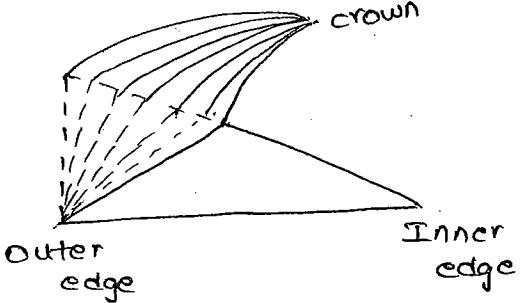
N = rate of introduction of super elevation

W = width of the pavement

W_e = extra width of the pavement

$W + W_e$ = total width of the pavement on horizontal curve.

b. pavement is rotated about inner shape:-



$$L = cN(w + w_c)$$

the crown is shifting slowly

iii) Emprec - Empirical formula given by IRC

$$\text{length of the transition curve} = L = \frac{2.7v^2}{R} \quad (\text{plain terrain})$$

$$L = \frac{v^2}{R} \quad (\text{mountain terrain})$$

The maximum of above three is the actual length of transition curve

P.Q NO:- 32

$$3. C = \frac{80}{75+v}$$

$$v = 100 \text{ kmph}$$

$$C = \frac{80}{75+100} \Rightarrow \frac{80}{175} = 0.457$$

$$4. L = \frac{v^3}{CR}$$

$$C = 0.3 \quad v = 15$$

$$R = 300$$

$$L = \frac{15^3}{0.3 \times 300}$$

$$= 37.5 \text{ m}$$

$$5. N = 120$$

$$e = \frac{1}{15}$$

$$w + w_e = 10 \text{ m}$$

$$L = eN(w + w_e)$$

$$= \frac{1}{15} (120) \times 10$$

$$= 80 \text{ m}$$

$$6. L = \frac{V^2}{R}$$

$$V = 100$$

$$R = 100$$

$$= \frac{100^2}{100}$$

$$L = 100 \text{ m}$$

$$7. C = \frac{80}{75 + V}$$

$$\therefore V = 80 \text{ kmph}$$

$$= \frac{80}{75 + 80}$$

$$= 0.52$$

Shift of the curve:- when transition curve is

When transition curve is introduced at the horizontal curve it is necessary to shift the main circular curve to inside of the curve.

$$S = \frac{L^2}{24R}$$

L = length of transition curve in 'm'

R = Radius of the curve in 'm'.

Ex:- A two lane pavement in plane terrain with extra widening 0.2m is provided on a horizontal curve of radius 200m the rate of change of centrifugal acceleration is $0.6 \frac{\text{m}}{\text{ss}}$. The rate of change of introduction of super elevation is 100. Design speed 60 kmph. The pavement is rotated about inner edges to achieve super elevation. Then the length of transition curve in 'm' is.

(25)

A. i) Rate of change of centrifugal acceleration, $c = 0.6 \text{ m/s}^2$

$$L = \frac{0.0215 v^3}{c R}$$
$$= \frac{0.0215 \times 60^3}{0.6 \times 200}$$

$$L = 38.7 \text{ m}$$

ii) Rate of introduction of super elevation. Pavement is rotated about inner edges

$$L = e N (w + w_e)$$

For plain terrain, $e = 0.07$ (assume)

$$N = 100$$

$$w + w_e = (7 + 0.2 \text{ m}) = 7.2 \text{ m}$$

↑
two lane road ↗ extra widening

$$L = 0.07 \times 100 (7.2)$$
$$= 50.4 \text{ m}$$

iii)

$$L = \frac{2.7 v^2}{R}$$
$$= \frac{2.7 (60)^3}{200}$$
$$= 48.6 \text{ m}$$

Longer of transition curve is, $L = 50.4 \text{ m}$

Ex:- calculate the value of shift of main circular curve in m.

A) $s = \frac{L^2}{24R}$

$$= \frac{(50.4)^2}{24 \times 200}$$
$$= 0.528 \text{ m}$$

UNIT - IV

Gradient :-

Slope provided along the longitudinal direction of pavement
is known as Gradient.

(26)

Terrain	Ruling gradient	Limiting gradient	Exceptional gradient
plain terrain	1 in 30	1 in 20	1 in 15
Mountain terrain	1 in 20	1 in 16.7	1 in 14.3

→ Maximum length of the road is provided with ruling gradient therefore it is known as design gradient.

→ The steeper gradient i.e., exceptional gradient is limited for shorter distances not exceeding about 60m in 1 km length of the road.

Grade compensation:-

Reduction in gradient at the horizontal curve is known as Grade compensation.

$$G.C = \frac{30+R}{R}$$

R = Radius of the curve in 'm'.

$$\text{Max G.C} = \frac{75}{R}$$

R = Radius of the curve in 'm'.

Compensated gradient on horizontal curve is equal to ruling gradient - grade compensation.

Note:-

As per limitation of IRC grade compensation is not necessary for gradient flatter than 4%. i.e. gradient need not be eased beyond 4% (1 in 25)

1. Grade compensation, $G.C = \frac{30+R}{R}$
 $= \frac{30+150}{150} = 1.2\%$

$$\text{Max } G.C = \frac{75}{150} = 0.5\%$$

$\therefore G.C$ is considered 0.5

2. $G.C = \frac{30+R}{R}$
 $= \frac{30+30}{30} = 2\%$
 $\therefore G.C = 2\%$

$$\text{Max } G.C = \frac{75}{R}$$
 $= \frac{75}{30} = 2.5\%$

considered $G.C = 2\%$

compensated gradient on horizontal curve $= (1 \text{ in } 20) - 2\%$
 $= 5\% - 2\%$
 $= 3\%$
 $\therefore G.C = 1 \text{ in } 33.33$

so don't consider $1 \text{ in } 33.33$,
as per IRC considered $1 \text{ in } 25$

13. $R = 60 \text{ m}$

$$G.C = \frac{30+60}{60} = 1.5\%$$

$$\text{Max } G.C = \frac{75}{60} = 1.25\%$$

Take $G.C = 1.25\%$.

6. $G = 2C$
 $C = \frac{1}{2}G$

$$\text{camber} = 1 \text{ in } 48$$

$$\text{gradient} = 1 \text{ in } 24$$

7. $G.C = \frac{30+R}{R}$
 $= \frac{30+80}{80} = 1.375$

$$\text{Max } G.C = \frac{75}{80} = 0.94$$

$$\text{Take } G.C = 0.94\%$$

$$\text{Ruling gradient} = 5\% = 1 \text{ in } 20$$

compensated gradient
 $= \text{Ruling gradient} - G.C$
 $= 5 - 0.94$
 $= 4.06\%$
 $\therefore G.C = 1 \text{ in } 25$

Ruling Gradient = 6%.

compensated gradient = $6 - 1.25$

$$= 4.75 \%$$

$$= 1 \text{ in } 20$$

(27)

Transition curve :-

The geometric design features considered from the starting of design transition curve are

- i) Super elevation
- ii) Extra width of pavement
- iii) Grade compensation.

UNIT - IX

Set back distance :-

The distance free from obstructions provided inner side of the curve is known as set back distance.

(i) Length of the curve is ($L > SD$) greater than sight distance

ii) consider certain portion of horizontal curve, radius of the curve

a. i) consider single lane road

$$m = R - R \cos(d/2)$$

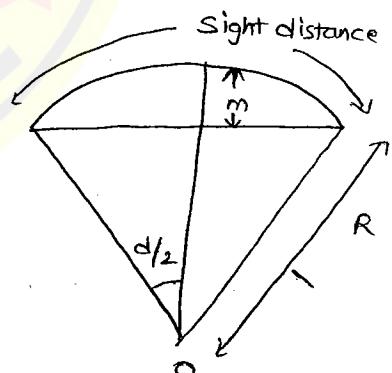
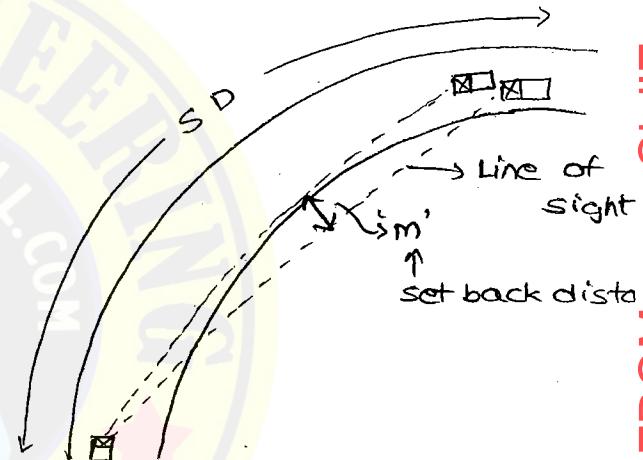
$$\frac{d}{2} = \frac{180S}{2\pi R}$$

b. Multilane road

$$\frac{d}{2} = \frac{180S}{2\pi R}$$

$$m = R - (R-d) \cos \frac{\alpha}{2}$$

$$\frac{\alpha}{2} = \frac{180S}{2\pi R}$$



d = distance b/w centre line of the road and centre of inside lane of the road.

$$d = \frac{w}{4}$$

w = width of the road

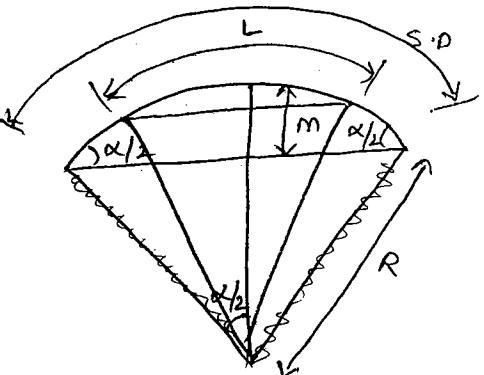
$$d = \frac{\frac{w}{2}}{2} \Rightarrow \frac{w}{4}$$

ii) length of the curve is less than sight distance : - (L < SD)

a) For single lane road

$$m = R - R \cos \frac{\alpha}{2} + \frac{s-l}{2} \sin \frac{\alpha}{2}$$

$$\frac{\alpha}{2} = \frac{180L}{2\pi R} \text{ degrees}$$



b) consider multilanes

$$m = R - (R-d) \cos \frac{\alpha}{2} + \frac{s-l}{2} \sin \frac{\alpha}{2}$$

$$\frac{\alpha}{2} = \frac{180L}{2\pi(R-d)}$$

$$d = \frac{w}{4}$$

Approximate formula :-

1. L > SD (s)

$$m = \frac{s^2}{8R}$$

2. L < SD (s)

$$m = \frac{L(2s-L)}{8R}$$

P.9 NO:- 30.

Q. SD = 80 m

$$m = 10 \text{ m}$$

$$R = ?$$

$$m = \frac{s^2}{8R}$$

$$10 = \frac{80^2}{80 \times R} \Rightarrow R = 80 \text{ m}$$

The loss of tractive force due to turning of a vehicle
on horizontal curve, $\varphi = T(1 - \cos \alpha)$

(28)

T = Tractive force on vehicle.

α = Turning angle

$$1) \Rightarrow \frac{T(1 - \cos \alpha)}{\varphi}$$

$$\Rightarrow T(1 - \cos 45^\circ)$$

$$\Rightarrow 0.292 T$$

$$2) T(1 - \cos 30)$$

$$= 0.1338 T$$

$$3) T(1 - \cos 90)$$

$$= T.$$

UNIT - XI

Verticle curves:-

Verticle curves are classified into two types

- 1) summit (or) crest curve
- 2) valley (or) sag curve.

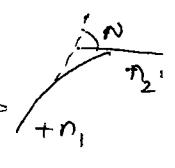
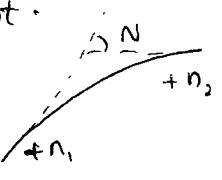
Summit curves:-

Summit curves are formed in any one of the following combination.

1. A upgradient meeting with another upgradient.
2. Upgradient generally denoted with ' N ' $\cong n, -n_2$
3. ' N ' is deviation angle or deflection angle.
4. Angle at the intersection of two gradients
5. A upgradient meeting with level surface $N = n, \cancel{-n_2}$
6. A upgradient meeting with down gradient

$$N = n, -(-n_2)$$

$$= n + n_2$$



4. A down gradient meeting with another down gradient

$$N = -n_1 - (-n_2)$$

$$N = n_2 - n_1$$



The maximum deviation angle is found in third case.

Factors considered for design of summit curve:-

1. When a vehicle moving on a summit curve the centrifugal force will act upward direction therefore there is no problem of discomfort to the passengers.
2. provide adequate sight distance i.e., stopping sight distance and OSD

3. Length of the summit curve:-

i. ~~if~~ SSD:-

a) $L > SSD (s)$

$$L = \frac{Ns^2}{(\sqrt{2H} + \sqrt{2h})^2}$$

N = deviation angle or deflection angle

s = stopping sight distance

H = Height of high level of driver = 1.2 m

h = height of object = 0.15 m

$$\boxed{L = \frac{Ns^2}{4 \cdot 4}}$$

b) $L < SSD (s)$

$$L = \frac{2s - (\sqrt{2H} + \sqrt{2h})^2}{N}$$

$H = 1.2 \text{ m}$

$h = 0.15 \text{ m}$

$$\boxed{L = \frac{2s - 4 \cdot 4}{N}}$$

2. Overtaking sight distance (OSD) :-

a. $L > OSD (S)$:-

$$L = \frac{NS^2}{(\sqrt{2H} + \sqrt{2h})^2}$$

$$H = h = 1.2 \text{ m}$$

$$\boxed{L = \frac{NS^2}{9.6}}$$

b. $L < OSD$

$$L = 2s - \frac{(\sqrt{2H} + \sqrt{2h})^2}{N}$$

$$\boxed{L = 2s - \frac{9.6}{N}}$$

Note:-

1. Simple parabolic curve is used as a summit curve
2. The radius of simple parabolic curve, $R = L/N$

P.Q NO:- 35

1. $S = 120 \text{ m}$

$H = 1.5 \text{ m}$

$h = 0.15 \text{ m}$

$N = 0.09$

$L > SD (S)$

$$\therefore L = \frac{NS^2}{(\sqrt{2H} + \sqrt{2h})^2}$$

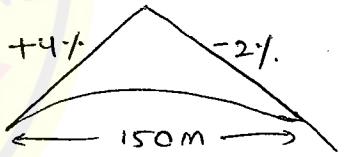
$$= \frac{0.09 (120)^2}{(\sqrt{2 \times 1.5} + \sqrt{2 \times 0.15})^2}$$

$$= 249.35 \text{ m}$$

$$L \approx 250 \text{ m} \quad (\text{Hence satisfied})$$

$$\therefore (L > SD)$$

4.



$$N = +4 - (-2) = 6\%$$

$$6\% \rightarrow 150 \text{ m}$$

$$4\% \rightarrow ?$$

$$\Rightarrow \frac{4 \times 150}{6} = 100 \text{ m}$$

At 100m, get a highest point

5. Raising gradient = $+\frac{1}{50}$
 downward gradient = $-\frac{1}{100}$

$$N = \frac{1}{50} - \left(-\frac{1}{100}\right)$$

$$= 3\%$$

Given $1\% \rightarrow 100 \text{ m}$

$3\% \rightarrow ?$

$$\Rightarrow \frac{3 \times 100}{1} = 300 \text{ m}$$

7. Raising gradient = $+\frac{1}{25}$

Falling gradient = $-\frac{1}{25}$

$$N = \frac{1}{25} - \left(-\frac{1}{25}\right)$$

$$= 0.08$$

Given OSD = 300 m

consider, $L > OSD$

$$L = \frac{NS^2}{9.6}$$

$$= \frac{0.08 \times (300)^2}{9.6}$$

$$L = 750 \text{ m}$$

10. Raising gradient = $+3\%$.

Falling gradient = -5% .

$$N = 3 - (-5)$$

$$= 8\%$$

$$= 0.08$$

consider $L > SSD$

$$L = \frac{NS^2}{4.4} = \frac{0.08 \times (128)^2}{4.4}$$

$$= 298 \text{ m}$$

6. Raising gradient = $+\frac{1}{25}$
 Falling gradient = $-\frac{1}{50}$

$$N = \frac{1}{25} - \left(-\frac{1}{50}\right)$$

$$= 0.06$$

Given SSD = 100 m

consider $L > SSD$

$$L = \frac{NS^2}{(\sqrt{2H} + \sqrt{2h})^2}$$

$$\text{let } H = 1.2 \quad h = 0.15$$

$$L = \frac{NS^2}{4.4}$$

$$L = \frac{0.06 \times 100^2}{4.4} = 136.4 \text{ m}$$

\therefore Hence satisfied.

8. Raising gradient = $+\frac{1}{50}$

Falling gradient = $-\frac{1}{25}$

$$N = \frac{1}{25} - \left(\frac{1}{50}\right)$$

$$= \left| -\left(\frac{1}{25} + \frac{1}{50} \right) \right|$$

$$= | -0.06\% |$$

$$= 0.06\%$$

Given $0.3\% \rightarrow 20 \text{ m}$

~~$0.06\% \rightarrow x \text{ m}$~~

$$x = \frac{20 \times 0.06}{0.3}$$

$$= 400 \text{ m}$$

$$\text{II. Raising gradient} = \frac{1}{100}$$

$$\text{Falling gradient} = -\frac{1}{50}$$

$$N = \frac{1}{100} - \left(-\frac{1}{50}\right)$$

$$= 0.03$$

Given OSD = 500 m

consider $L > \text{OSD}$

$$L = \frac{NS^2}{9.6}$$

$$= \frac{0.03 (500)^2}{9.6}$$

$$L = 781 \text{ m}$$

UNIT - XII

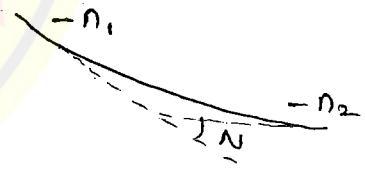
Valley curve (or) Sag curve :-

Valley curves are formed in any one of the following combinations.

1. A down gradient meeting with another down gradient

$$N = -n_1 - (-n_2)$$

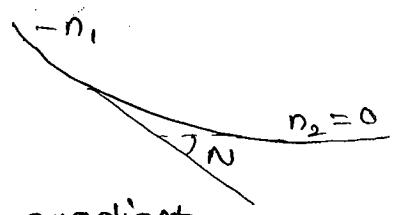
$$N = n_2 - n_1$$



2. A down gradient meeting with level surface.

$$N = |-n_1 - 0|$$

$$N = n_1$$

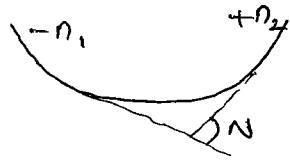


3. A down gradient meeting with up gradient

$$N = |-n_1 - n_2|$$

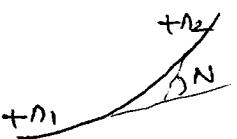
$$= |-(n_1 + n_2)|$$

$$N = n_1 + n_2$$



4. A upgradient meeting with another upgradient

$$N = \alpha_1 - \alpha_2$$



Note:-

The maximum deviation angle is observed in the third case.

Factors considered for design of valley curve:-

- When a vehicle moving on valley curve the centrifugal force will act downward direction therefore it is discomfort to the passengers. Hence considered the impact free moment of vehicles at the design speed.
- Availability of stopping sight distance under head lights during night time.
- OSD is prohibited in valley curve.
- SSD is taken as Head light sight distance.

Length:-

- By considering rate of change of centrifugal acceleration.

$$L = 2 \left(\frac{NV^3}{C} \right)^{1/2}$$

N = Deflection angle

V = Speed of vehicle in m/sec

C = Rate of change of centrifugal acceleration in m/s^3 .

$$C = 0.6 \text{ m/sec}^3$$

$$L = 2 \left(\frac{NV^3}{C} \right)^{1/2}$$

V in kmph.

$$L = 0.38 (NV^3)^{1/2}$$

- HLSD = SSD

$$\alpha = L > HLSD(s)$$

$$L = \frac{Ns^2}{(2h_1 + 2s \tan \alpha)}$$

$$L = \frac{Ns^2}{(1.5 + 0.035s)}$$

$$S = 550$$

h_1 = height of head light above the road surface

$h_1 = 0.75\text{m}$ generally

α = Head of light angle

$$\alpha = 1^\circ$$

(b) $L < H LSD$

$$L = (2s - \frac{2h_1 + 2s \tan \alpha}{N})$$

$$L = 2s - \frac{1.5 + 0.035s}{N}$$

→ The best shape of valley curve is cubic parabola.

→ The minimum radius of valley curve $R = \frac{L}{2}$

Impact Factor (I):-

The ratio of centrifugal force to the weight of vehicle

$$I = \frac{P}{W}$$

$$I = \frac{1.6 N V^2}{L}$$

$$N \neq \phi$$

V in kmph

L in m.

P.g No:- 38

$$3. n_1 = -0.04 \quad n_2 = +0.025$$

$$N = |-0.04 - 0.025|$$

$$N = 0.065$$

(i) $L > H LSD$

$$L = \frac{Ns^2}{(1.5 + 0.035s)} = \frac{0.065 \times 100^2}{(1.5 + 0.035 \times 100)} = 130\text{m} > 100\text{m} (\text{H LSD})$$

$$2. C = 0.6 \text{ m/sec}^3 \quad n_1 = -0.04 \quad n_2 = +0.05$$

$$N = -n_1 + 0.05$$

$$= |-0.09|$$

$$N = 0.09$$

(i) comfort condition :-

$$L = 0.38 (NV^3)^{1/2}$$

$$= 0.38 (0.09 \times 100^3)^{1/2}$$

$$L = 114 \text{ m}$$

(ii) HLSD = 180 m

a. $L > HLSD$

$$\begin{aligned} L &= \frac{NS^2}{(1.5 + 0.035S)} \\ &= \frac{0.09 \times 180^2}{(1.5 + 0.035 \times 180)} \end{aligned}$$

$$L = 373.84 \text{ m}$$

Take max. of these two L values

(iii) calculate impact factor for above values (I) :-

$$\begin{aligned} I &= \frac{1.6 NV^2}{L} \\ &= \frac{1.6 \times 0.09 \times 100^2}{373.84} \end{aligned}$$

$$I = 3.85$$

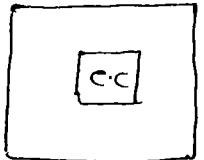
UNIT - I
HIGHWAY PLANNING

(32)

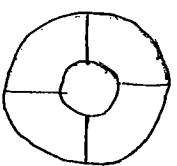
The classification based on location and function by Nagpur Road plan is as follows.

1. National Highway
2. SH
3. MDR
4. DDR
5. VR

1. Rectangular or block pattern is adopted in the city of Chandigarh.



2. Radial and circular pattern is similar to the road network of Cannaught place in New Delhi.



3. Master plan is the final development of road in urban areas by taking into consideration of future expansion and requirements.

4. First 20 years road plan is Nagpur road plan (1943 - 1963).
5. Second 20 years road plan is Bombay road plan (1961 - 81).
6. Third 20 years road plan is Lucknow road plan (1981 - 2001).

→ Jayakar Committee as suggested three recommendations.

- a. Collect Central Road Fund (CRF)
- b. Formation of IRC
- c. Formation of Indian Motor Vehicle Act.

IRC 1934:-

For specifications, standardization and Recommendation on materials, design and construction of road and bridges.

CRRI (1950):-

Research in various aspects of highway Engineering.

Saturation system (or) Maximum utility system:-

It is useful in deciding the best road system based on alternative proposals.

In this system the optimum road length is calculated based on maximum utility per unit length of the road.

The factors considered are

- a. population
- b. Agricultural and Industrial productivity.

Three new roads P, Q, and R planned in a given area based on principle of maximum utility- the order of priority for these three roads should be

Road	Length	No. of villages with population	utility	
P	20	< 2000	2000 - 5000	> 5000
Q	28	8	6	1
R	12	19	8	4
		7	5	2

Sol:- weightage factor $10 \cdot 5$ 1 2

Less population less weightage factor

$$P = \frac{12}{20} = 0.6 \quad \text{III}$$

$$Q = \frac{25 \cdot 5}{28} = 0.91 \quad \text{II}$$

$$R = \frac{12 \cdot 5}{12} = 1.04 \quad \text{I}$$

} Utility per unit length.

UNIT - XIII
HIGHWAY MATERIALS

(33)

Based on structural behaviour

1. Flexible pavement (or) Bituminous pavement (or) Black top road
2. Rigid pavement (or) cement concrete pavement (or) white top road

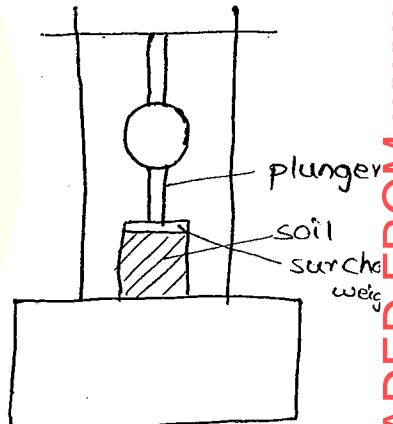
Sub grade soil characteristics :-

CBR Test:-

It is an empirical method by considering physical properties and strength parameters of sub grade soil for design of flexible pavement.

CBR percentage is calculated at 2.5 mm and 5.0 mm penetration.

Time	penetration mm	proving ring reading	Load kg.
1 min	1.25	x_1	y_1
2 min	2.5	x_2	y_2
3 min	3.75	x_3	y_3
4 min	5.0	x_4	y_4
5 min	6.25	x_5	y_5



$$\text{CBR \%} = \frac{\text{Load carried by soil specimen at given penetration}}{\text{Load carried by aggregates at the same penetration}} \times 100$$

$$\begin{aligned}
 \text{(i) CBR \% @ 2.5 mm} &= \frac{\text{Load carried by soil specimen @ 2.5 mm}}{\text{Load carried by aggregates @ 2.5 mm}} \times 100 \\
 &= \frac{y_2}{1370} \times 100
 \end{aligned}$$

Load carried by aggregates @ 2.5 mm penetration = 1370 kgs.

$$(ii) \text{ CBR \% @ } 5.0 \text{ mm} = \frac{y_4}{2055} \times 100$$

Load carried by aggregates @ 5.0 mm penetration = 2055 kgs.

$$\text{CBR \% @ } 2.5 \text{ mm} > \text{CBR \% @ } 5.0 \text{ mm}$$

→ The maximum of these two values is actual CBR % of subgrade soil.

$$\text{Area of plunger (A)} = 19.6 \text{ cm}^2$$

$$\text{pressure created by plunger} = P$$

$$\text{Load} = \frac{P}{A}$$

As the CBR value increases the required thickness of pavement will be decreases.

Ex:-) The following test results were obtained by CBR test on subgrade soil. Then CBR of soil is.

Penetration	2.5	5.0
Load	55	78

$$A) \text{ CBR @ } 2.5 \text{ mm} = \frac{55}{1370} \times 100 \\ = 4.01 \%$$

$$\text{CBR @ } 5.0 \text{ mm} = \frac{78}{2055} \times 100 \\ = 3.79 \%$$

$$\boxed{\text{CBR of soil} = 4.01 \%}$$

→ The function of surcharge weights is to (equal distribution of load) (or) simulate the effect of flexible pavements.

Plate bearing test:-

This test is used to find a) modulus of subgrade reaction (K) b) Modulus of elasticity of soil (E).

Modulus of subgrade reaction (K):-

75 cm ϕ plate is used in this test.

The pressure sustained for unit deformation of subgrade soil.

$$K = \frac{\text{Pressure}}{\frac{\text{Deformation (or)} \\ \text{Settlement}}{\text{Settlement}}} = \frac{\text{kg}}{\text{cm}^2/\text{cm}} = \frac{\text{kg}}{\text{cm}^3}$$

a. 0.7 kg/cm² (P) to settlement.

Standard pressure 0.7 kg/cm² and standard settlement 1.25 mm are considered for this experiment.

If smaller size of the plate 30 cm ϕ plate is used to find K value then the relation is K corresponding to 75 cm ϕ is equal to K corresponding to 30 cm $\phi \times 0.5$.

$$K_{75 \text{ cm } \phi} = K_{30 \text{ cm } \phi} \times 0.5$$

The modulus of subgrade reaction (K) is used in design of rigid pavement i.e., C.C. pavement.

Modulus of elasticity of subgrade soil:- (E)

$$E = \frac{1.18 \text{ pa}}{\delta}$$

where

P = pressure or stress in kg/cm²

a = Radius of plate in cm

δ = Deformation or settlement in cm

$$E = \text{kg/cm}^2.$$

Ex:- Modulus of Elasticity subgrade reaction using 30 cm ϕ plate is 200 N/cm 3 the value of same using standard plate will be.

$$\text{A) } K_{75 \text{ cm} \phi} = K_{30 \text{ cm} \phi} \times 0.5 \\ = 200 \times 0.5 \\ = 100 \text{ N/cm}^3$$

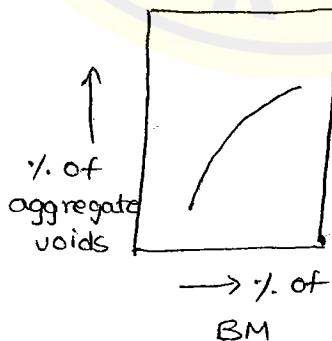
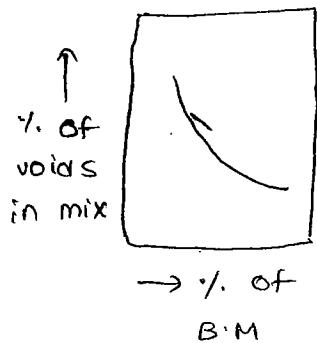
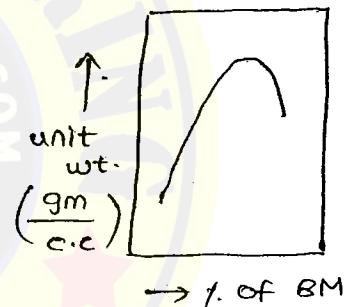
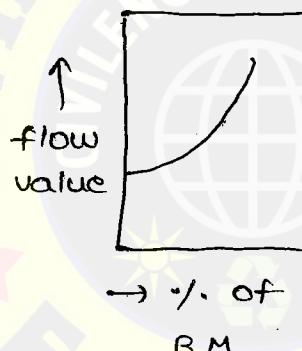
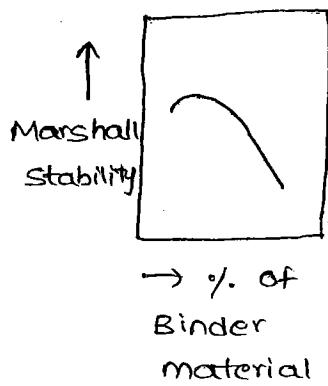
Ex:- A plate load test conducted with a 75 cm ϕ plate on soil sub grade given a deflection of 2.5 mm under a stress of 800 N/cm 2 . The modulus of elasticity of subgrade soil in KN/cm 2 is

$$\text{A) } \delta = 2.5 \text{ mm} = 0.25 \text{ cm} \\ a = \frac{75 \text{ cm} \phi}{2} = 37.5 \text{ cm} \\ P = 800 \text{ N/cm}^2 \\ E = \frac{1.18 \text{ pa}}{8} = \frac{1.18 \times 800 \times 37.5}{0.25} \\ = 141600 \text{ N/cm}^2 \\ E = 141.6 \text{ KN/cm}^2$$

Marshall stability test

1. This test is used for hot mix process for design of bituminous mixes scientifically.
2. The optimum binder content for the given type of aggregates is the average of the binder content corresponding to maximum stability, max bulk density and percent air voids. 3 to 5.
3. The material used for bituminous construction are coarse aggregate and fine aggregate filler material and binder material.

The graphs for different parameters of marshall stability test are as follows:



4. The theoretical sp. gravity of the mix = $\frac{100}{\frac{w_1}{G_1} + \frac{w_2}{G_2} + \frac{w_3}{G_3} + \frac{w_4}{G_4}}$

where, w_i = % weight of coarse aggregate,

G_i = sp. gravity of coarse aggregate.

w_2 = % weight of fine aggregate

a_2 = sp. gravity of fine aggregate.

w_3 = % weight of filler material.

a_3 = sp. gravity of filler material

w_4 = % weight of binder material

a_4 = sp. gravity of binder material.

5. percentage of volume of air voids (v_a) = $\frac{a_t - a_m}{a_m} \times 100 \%$.

where, a_t = theoretical unit wt. of mix.

a_m = measured unit wt. of mix

6. volume of binder material (v_b) = $\frac{w_b}{a_b} \times a_m \%$.

where, w_b = % weight of binder material

a_b = sp. gravity of binder material

a_m = measured unit weight.

7. voids in mineral aggregates - (VMA) = $v_a + v_b \%$.

8. voids filled with binder material (VFB) = $\frac{v_b}{v_{MA}} \times 100$

Ex:- In the marshall method of mix design the coarse aggregates, fine aggregates filter material and bitumen having respective sp. gravities 2.62, 2.72, 2.7 and 1.02 are mixed in the ratio, of 55, 34.6, 4.8 and 5.6%. The theoretical sp. gravity of the mix is?

$$\begin{aligned} A. \text{ Theoretical sp. gravity} &= \frac{100}{\frac{w_1}{a_1} + \frac{w_2}{a_2} + \frac{w_3}{a_3} + \frac{w_4}{a_4}} \\ &= \frac{100}{\frac{55}{2.62} + \frac{34.6}{2.72} + \frac{4.8}{2.7} + \frac{5.6}{1.02}} \\ &= 2.44 \end{aligned}$$

Ex:- The specific gravities and weight of different materials used for preparation of Marshall mould are given below. The volume and weight of marshall mould are 475 cm^3 and 1100 gm respectively. Find voids filled with bitume.

A.

	A_1	A_2	A_3	A_4	Bitumen
wt. (gm)	825	1200	325	150	100 $\Rightarrow 2.61$
sp. gravity	2.63	2.51	2.46	2.43	1.05 $\downarrow G_b$

A. Theoretical sp. gravity =

$$\frac{100}{\frac{w_1}{G_1} + \frac{w_2}{G_2} + \frac{w_3}{G_3} + \frac{w_4}{G_4} + \frac{w_5}{G_5}}$$

$$= \frac{100}{\frac{825}{2.63} + \frac{1200}{2.51} + \frac{325}{2.46} + \frac{150}{2.43} + 1.05}$$

$$A_1 \% \Rightarrow \frac{825 \times 100}{2600} = 31.7 \%$$

$$A_2 \% \Rightarrow \frac{1200 \times 100}{2600} = 46.15 \%$$

$$A_3 \% \Rightarrow \frac{325 \times 100}{2600} = 12.5 \%$$

$$A_4 \% \Rightarrow \frac{150 \times 100}{2600} = 5.7 \%$$

$$\text{bitumen} \Rightarrow \frac{100 \times 100}{2600} = 3.8 \% \Rightarrow w_b$$

Theoretical unit sp. gravity =

$$\frac{100}{\frac{31.7}{2.63} + \frac{46.15}{2.51} + \frac{12.5}{2.46} + \frac{5.7}{2.43} + 1.05}$$

$$= \frac{100}{12 + 18.38 + 5.08 + 2.34 + 3.61}$$

$$= \frac{100}{41.41}$$

$$= 2.41$$

Theoretical unit weight (γ_t) = 2.4 gm/cc

$$G_M = \frac{1100}{475} = 2.31$$

$$\begin{aligned}\% \text{ of voids } (V_a) &= \frac{\gamma_t - G_M}{G_M} \times 100 \\ &= \frac{2.4 - 2.31}{2.31} \times 100 \\ &= 3.89 \%\end{aligned}$$

$$\begin{aligned}\text{volume of binder bitumen } (V_b) &= \frac{W_b}{G_b} \times G_M \\ &= \frac{3.8}{1.05} \times 2.31 \\ &= 8.36\end{aligned}$$

$$\begin{aligned}\text{voids in mineral aggregates} &= 3.89 + 8.36 \quad (V_a + V_b) \\ &= 12.26 \%\end{aligned}$$

$$\begin{aligned}\text{voids filled with binder material} &= \frac{V_b}{VMA} \\ &= \frac{8.36}{12.26} \times 100 \\ &= 68.24 \%\end{aligned}$$

Ex:- A bitumen mixer contain 60% coarse aggregate, 35% fine aggregate, 5% bitumen. Find unit wt. of the mixer after compaction with 7% air voids. sp. gravity of coarse aggregate 2.72, sp. gravity of fine aggregate 2.66, sp. gravity of bitumen 1.0.

$$\begin{aligned}A. \text{ Theoretical sp. gravity of the mix} &= \frac{100}{\frac{60}{2.72} + \frac{35}{2.66} + \frac{5}{1.0}} \\ &= 2.48\end{aligned}$$

Theoretical unit wt. of the mix (γ_t) = 2.48 gm/cc

$$V_a = \frac{\gamma_t - G_M}{G_M} \times 100$$

$$7 = \frac{2.48 - G_M}{G_M} \times 100$$

$$7G_m + \frac{100}{G_m} = 248$$

$$G_m = \frac{248}{107}$$

$$G_m = 2.32 \text{ gm/cm}^3.$$

* Tests on aggregate :-

1. Crushing test :- (strength)

$$\text{Crushing value of aggregate} = \frac{\text{Powder wt.}}{\text{Initial wt. of aggregate}} \times 10$$

- A total load of 40 tons @ 4 tons/min is applied for 25 to 10 mm size of aggregate and 10 tons at the rate of 1 ton/min is applied for below.
- Base coarse of cement concrete road should not exceed 45% and surface courses should not exceed 30%.

2. Impact test :-

Impact test is used for toughness of aggregates
Resistance to sudden application of loads is toughness

- 13.5 to 14 kg weight of hammer, height of fall of hammer 38 cm and 15 blows
- For base courses of cement concrete road should not exceed 45% and surface coarse should not exceed 30%.
- The aggregate crushing and impact value are similar closing the within limits are majority of aggregates. But in case of fine grained highly siliceous aggregates the impact values are higher than crushing value.

3. Abrasion test:-

Abrasion test is used for Hardness of aggregates. Rubbing action between two materials is known as Abrasion.

Abrasive charge in the form of steel balls used in this test.

- a. Los angeles abrasion
- b. Darry abrasion
- c. Deval abrasion

A	grade of aggregate	5 kg	500 rpm
B	C		
D	E	10 kg	1000 rpm
F	G		

- The maximum value of abrasion for surface courses both for bituminous and cement concrete road is 30%.
- Surface coarse of WBM is 40%.
- Attrition means the rubbing action between same materials.
- The deval abrasion test is used for finding abrasion value of aggregates without using steel balls.

4. Shape test:-

The shape test are

- 1) Flakiness index
- 2) Elongation index
- 3) Angularity number.

Flakiness index:-

the percentage weight of aggregate whose least dimension or thickness is less than 0.6 times mean dimension of aggregates.

1. passing weight of aggregates is considered
2. Then Flakiness Index (FI) = $\frac{\text{Total passing wt. of aggregate}}{\text{Total wt. of aggregates}}$
3. It is not applicable to below 6.3 mm size of aggregate
4. thickness gauge is used.

size of aggregate (mm):-

63-50 mm, 50-40, 40-31.5, 31.5-20, 20-16, 16-12.5
12.5 - 10, 10 - 6.3

width of the (63-50 mm) is $\frac{0.6(63+50)}{2} = 33.9 \text{ mm}$

width of the (50-40 mm) is $\frac{0.6(50+40)}{2} = 27 \text{ mm}$

Elongation Index:-

The percentage weight of aggregate whose greater dimension or length is greater than 1.8 times the mean dimension of aggregate.

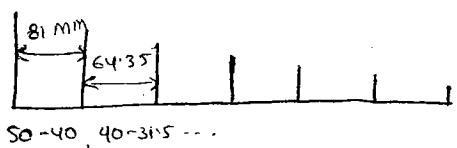
Retained weight of aggregates is considered.

Elongation index = $\frac{\text{Total retained weight of aggregates}}{\text{Total weight of aggregates}} \times 100$

It is not applicable to below 6.3 mm size of aggregate

→ Length gauge is used.

size of aggregate starting with 50-40 mm, 40-31.5 mm ...



$$\text{size of aperture} = \frac{1.8(50+40)}{2} = 81 \text{ mm}$$

$$\text{size of aperture} = \frac{1.8(40+31.5)}{2} = 64.35 \text{ mm}$$

Ex:- In a 500 gm sample of coarse aggregates there are 100 gm flaki particles and 80 gm elongated particles. What are the flakiness and elongation Indices in total is?

- a) 40%. b) 36%. c) 18%. d) 4%.

A) $FI = \frac{100}{500} \times 100 = 20\%$ } 40%
 $EI = \frac{80}{400} \times 100 = 20\%$

Note:- In flakiness index there are 100 particles are passed out of 500. the remaining 400 particles are used for Elongation index.

Angularity number:-

It denotes the void content of single size of aggregates in excess of that is obtained with spherical size of aggregates. It ranges from 0-11

$$\text{Angularity Number} = 67 - \frac{100W}{Ca}$$

w = weight of aggregate

c = weight of water

a = sp. gravity of aggregates

5. Water absorption test:-

It measures the porosity of the aggregate. Water absorption should be < 0.6%. designated for bituminous road surface.

The sp. gravity of the aggregates used for road construction ranges from 2.5 to 3.0

6. soundness test:-

(33)

It is used for resistance to weathering action.

Sodium sulphate and Magnesium sulphate solutions are used for this experiment. The average loss of weight after 10 cycle should not exceed 12% + when tested with sodium sulphate and 18% when tested with Magnesium sulphate.

7. stripping value of aggregates:-

IRC as specified the maximum stripping value 5% for the aggregates used for bituminous construction.

Silica a common mineral of Igneous rocks having greater attraction with water than bituminous binder material

Types of binder material used for bituminous construction:-

1. Bitumen :-

It is a hydro carbon obtain by fractional distillation of petroleum. It is soluble in carbon-di-sulphide and carbon tetrachloride.

2. Tar :-

It is obtain by destructive distillation of coal and wood in absence of air. It is soluble in toluene and free carbon content is more.

Road Tar, RT - 1 having low viscosity

RT - 2

:

RT - 5 having high viscosity

3. Asphalt :-

The natural available bitumen is called Asphalt. Bitumen contains certain minerals that is Asphalt. Bitumen, Tar, Asphalt are used for Hot mix process.

4. Cut back bitumen:-

When bitumen mixed with volatile diluent that is
called cut back bitumen
(or)
Solvent.

Types of cut back bitumen:-

① 1. Rapid curing cutback bitumen: (RC)

When bitumen is mixed with petroleum distillate such as naphtha (or) gasoline

2. Medium curing cutback bitumen: - (MC)

Bitumen is mixed with kerosene (or) Light diesel oil.

3. Slope curing cutback bitumen: - (SC)

When bitumen is mixed with high boiling point gas oils.

→ These are used in surface dressing bitumen macadam and soil bitumen stabilization.

5. Emulsions:-

Bitumen is suspended in a finely divided condition in water medium and stabilized with Emulsifier

The methods used for preparation of Emulsions

1. colloid mill method or High speed Mixer method.

Emulsions are used for maintenance and patch repair works. It also used in soil stabilization in desert areas.

Above two materials are used for cold mix process.

Ex:- RC 1, MC 1, SC 1 indicates three different cutback bitumen having same viscosity.

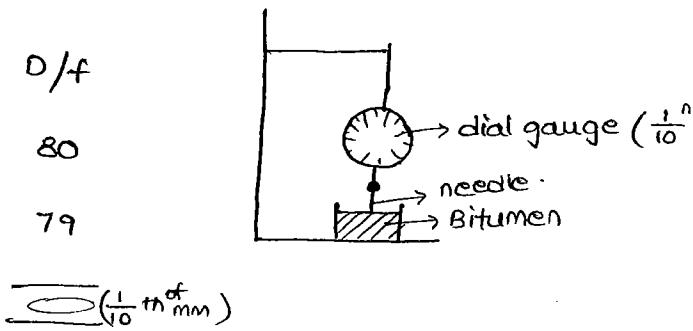
Tests on Binder Material :-

(40)

1. penetration test:-

It is used to find softness or Hardness of binder material.

Initial reading	Final reading	D/f
0	80	80
81	160	79



0 - 80 grade \Rightarrow Hard

80 - 225 grade \Rightarrow Medium

> 225 grade \Rightarrow Soft

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Ex:- A 45 indicates the penetration value of binder material lies between 40-50 and binder material is extracted from Assam refineries.

S25 indicates the binder material having penetration value ranges from 20 - 30 and binder material is extracted from other sources.

→ The standard test temperature is 25°C . The shape of tip of the needle is conical.

2. Ductility Test:-

Improving the physical interlocking of aggregates.

Briquette mould is used for conducting test. Minimum cross section of the Briquette mould is $10\text{ mm} \times 10\text{ mm}$. This mould is fixed at one end and other end is pulled under a pressure of 50 mm/min .

→ The ductility value should not be less than 50cm for bituminous construction.

3. Viscosity test:-

Inverse of fluidity is known as viscosity. It is expressed in terms of seconds. It is measured by finding the time taken by 50ml of the sample passing through specified orifice at a given temperature. Orifice viscometer is used for Tar and cut back bitumen.

Capillary tube viscometer is used for bitumen.

4. Specific gravity:-

The specific gravity of pure bitumen ranges from 0.97 to 1.02.

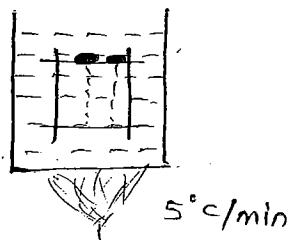
The specific gravity of tar ranges from 1.1 - 1.25.

- It measures the quality of binder material.
- In case the binder material contains certain impurities the specific gravity will be higher.
- Pycnometer method and balance method are used for finding specific gravity.

5. Softening point:-

The minimum temperature where the binder material having certain degree of softness.

- Ring and ball apparatus is used.
- When water heats, the ball fall down and touches the bottom plate. Note the temperature. That temperature is a softening point.
- For material softening point is above 80°C, glycerine is used as heating medium.



6. Flash and Fire point test:-

The lowest temperature where the vapour of substance catches the fire in the form of flash. The instrument used to conduct the test is Pensky Martens (or) closed cup and open cup are used for this test.

→ It will restrict the mixing temperature and application temperature well within the limits.

P.9 No:- 48

29. 1.8 Mean dimension for elongated test

$$1.8 \left(\frac{50+40}{2} \right)$$

$$= 81 \text{ mm}$$



2-11-2014

UNIT - 14

PAVEMENT DESIGN

Cross of a flexible pavement:-

The estimated traffic at
the end of design life of pavement

$$A = P(1+r)^{x+n}$$

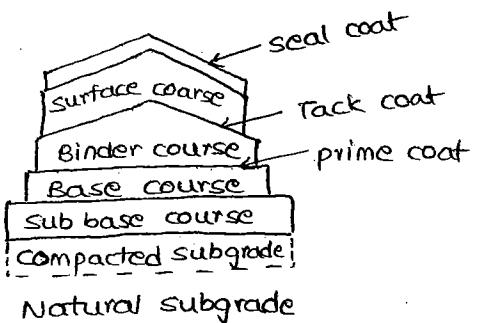
where,

P = at present traffic.

r = annual rate of growth of traffic.

x = time required for construction of road

n = design life of the pavement.



Contact pressure = $\frac{\text{wheel load}}{\text{contact area}}$

Rigidity factor = $\frac{\text{contact pressure}}{\text{tyre pressure}}$.

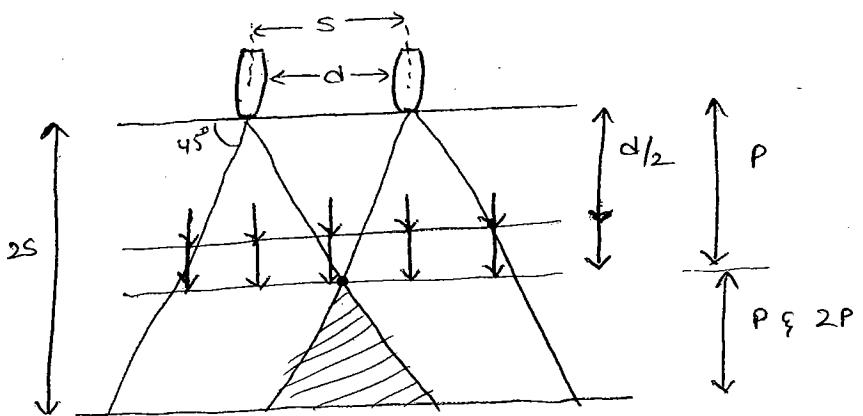
$R.F = 1$, for tyre pressure is 7 kg/cm^2

$R.F > 1$, for tyre pressure is low, $< 7 \text{ kg/cm}^2$

$R.F < 1$, for high tyre pressure $> 7 \text{ kg/cm}^2$

Equivalent single wheel load (ESWL):-

Multiple wheel load are converted to equivalent single wheel load and this value is used for design of pavements.



d = clear distance between two wheels

s = centre to centre distance between two wheels.

→ upto $d/2$ each wheel load be acting independently.
after this point the stresses induced due to each wheel load begins to overlap.

→ At any depth greater than ' s ' is considered to be equivalent to a single wheel load of magnitude $2 \times p$

P. Q NO:- 54.

$$d = 11 \text{ cm}$$

$$s = 27 \text{ cm}$$

$$P = 20440 \text{ N}$$

$$\frac{\log y_1 - \log y_0}{\log x_1 - \log x_0} = \frac{\log y_2 - \log y_0}{\log x_2 - \log x_0}$$

$$\frac{\log (40880) - \log (20440)}{\log (54) - \log (55)} = \frac{\log y_2 - \log (20440)}{\log (20) - \log (55)}$$

$$0.30 = \frac{\log y_2 - 4.31}{0.56}$$

$$\log y_2 = 0.168 + 4.31$$

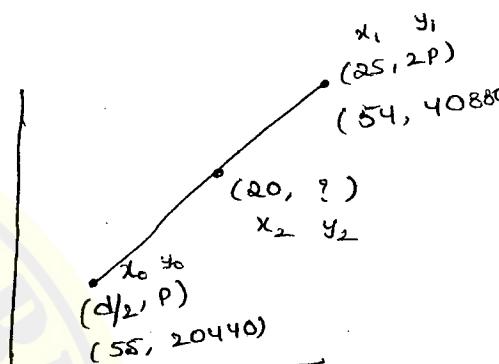
$$y_2 = 30190 \text{ N}$$

Design of flexible pavement:-

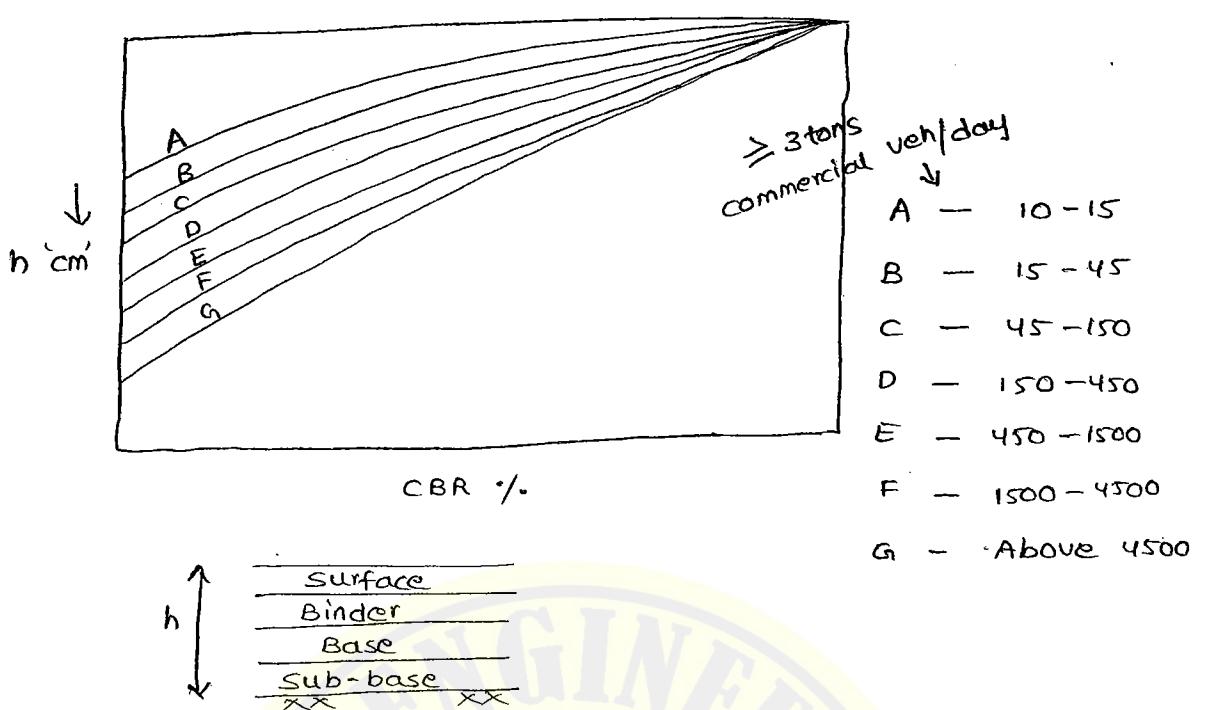
It transmit the load to the lower layers by grain to grain structure.

It reflect the deformation of the lower layers on to the surface of pavements.

Aggregate Interlocking property is major criteria for design of flexible pavement.



C.B.R. method for design of flexible pavement:-



IRC - 37 used for design of flexible pavements.

IRC - 37 - 1984 it is applicable to design traffic upto 30 million standard Axles.

IRC 37 - 2001 it is applicable to design traffic upto 150 million standard Axles.

The design traffic is considered in terms of cumulative no. of standard Axles i.e., denoted with N

$$N = \frac{365 \times A \times [(1+r)^n - 1] \times D \times F}{r}$$

where

A = initial traffic in the year of completion of road construction.

r = annual rate of growth of traffic.

D = lane distribution factor

F = vehicle damage factor.

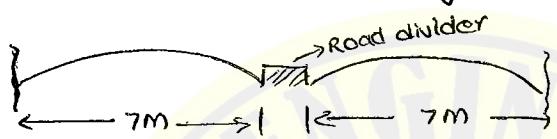
→ The lane distribution factor corresponding to the lane which is carrying maximum traffic.

1. For single lane road, lane distribution factor is 1
2. For two lane single carriage way is 7m, lane distribution factor is 0.75
3. Four lane single carriage way is 14m, lane distribution factor is 0.40

In above three cases the traffic moving in both the directions is considered.

4. Dual carriage way :-

- a. Dual two lane carriage way, lane distribution factor 0.75



- b. Dual three lane carriage way is 0.60

- c. Dual four lane carriage way is 0.45

In above case the traffic moving in one direction is considered.

Vehicle damage Factor (F) :-

Initial traffic volume (CV/day)	Terrain	
	plain	Mountainous
0 - 150	1.5	0.5
150 - 1500	3.5	1.5
>1500	4.5	2.5

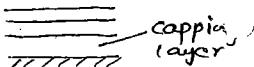
By using 'N' value and CBR (%) of subgrade soil refers the tables in IRC 37 - 2001.

1. Sub grade construction should have dry density greater than or equal to 1.75 gm/cm^3 .

2. C.B.R of sub grade soil is calculated at least for 3 samples for each type of soil.
3. The permissible maximum variation within the C.B.R. values from the three specimens is as follows.

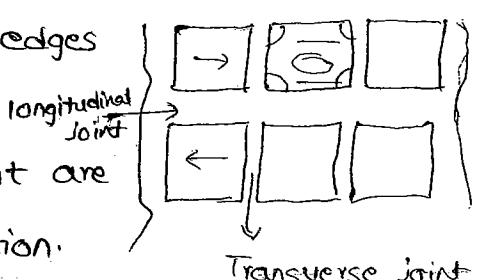
C.B.R (%)	Max. variation
upto 5	± 1
5 - 10	± 2
11 - 30	± 3
31 above	± 5

4. If variation is more than above values the design CBR value should be the average of atleast six samples.
5. If CBR value of the sub grade is less than 2%. A capping layer of thickness 150mm should be provided in addition to sub base course.
6. A blanket course of thickness 225 mm should be provided on the expansive soil sub grade as a sub-base course.
7. The top 50cm of sub grade is important for the design.
8. The CBR test should be performed on remoulded soil (disturbed soil) with static compaction



Design of Rigid pavement:-

- The flexural strength of concrete is major criteria for design of rigid pavement.
- The minimum characteristic compressive strength 280 kg/cm^2 .
min. F.S = 40 kg/cm^2 considered for design.
- The critical load positions are interior, edges and corner locations.
- The stresses caused in the rigid pavement are due to wheel load, temperature and friction.



Wester ghaurds stress equation due to wheel load:-

(44)

$$1. \quad s_i = \frac{0.316 P}{h^2} \left[4 \log_{10} \left(\frac{a}{b} \right) + 1.069 \right]$$

where

s_i = wheel load stress at interior location in kg/cm²

P = wheel load in kgs.

h = thickness of pavement in cms.

a = radius of relative stiffness in cm.

b = radius of resisting section in cm.

E = young modulus of concrete kg/cm²

K = modulus of sub grade reaction in kg/cm³

μ = poission ratio of concrete.

$$a = \left[\frac{E h^3}{12 K (1 - \mu^2)} \right]^{1/4}$$

$$b = \sqrt{1.6 a^2 + h^2} - 0.675 h \quad \text{when } \frac{a}{h} < 1.724$$

$$\frac{a}{h} > 1.724$$

$$b = a$$

a = radius of wheel load distribution in cm.

$$2. \quad s_e = \frac{0.572 P}{h^2} \left[4 \log_{10} \left(\frac{a}{b} \right) + 0.359 \right]$$

where

s_e = wheel load stress at edge location in kg/cm²

$$3. \quad s_c = \frac{3P}{h^2} \left[1 - \left(\frac{a\sqrt{2}}{b} \right)^{0.6} \right]$$

where

s_c = wheel load stress at corner location in kg/cm².

II. Temperature (or) warping stresses :-

$$1. \quad S_{t(i)} = \frac{E \cdot e \cdot t}{2} \left[\frac{c_x + \mu c_y}{1 - \mu^2} \right]$$

where

e = thermal expansion of concrete per $^{\circ}\text{C}$

t = temperature difference b/w top and bottom surfaces

c_x and c_y = warping stress coefficient

a_x = length of pavement section

a_y = width of pavement section

$$c_x = \frac{L_x}{8a} \quad] \text{ Design chart.}$$

$$c_y = \frac{L_y}{a}$$

$$2. \quad S_{t(e)} = \frac{c_x \cdot E \cdot e \cdot t}{2} \quad] \rightarrow \text{Max of two is considered.}$$

(or)

$$S_{t(e)} = \frac{c_y \cdot E \cdot e \cdot t}{2}$$

$$3. \quad S_{t(c)} = \frac{E \cdot e \cdot t}{3(1-\mu)} \times \sqrt{\frac{a}{l}}$$

III. Frictional stress :-

$$1. \quad S_f = \frac{w L f}{2 \times 10^4}$$

where

w = unit weight of concrete in kg/m^3

L = length of pavement section

f = coefficient of subgrade restraint,

critical combination of stresses :-

- critical combination of stresses at edges and interior locations when pavement is considered constructed in summer

$$= W \cdot S + T \cdot S - F \cdot S$$

$$\text{Interior} = S_i + S_{t(i)} - S_f$$

$$\text{edge} = S_e + S_{t(e)} - S_f$$

- critical combination of stresses at interior and edge location when pavement is constructed in winter

$$= WS + TS + FS$$

- critical combination of stresses at corner location

$$= W \cdot S + T \cdot S$$

Ex:- calculate the radius of relative stiffness in cm for following data. $E = 3 \times 10^5 \text{ kg/cm}^2$, $h = 18 \text{ cm}$, $\mu = 0.15$
 $K = 6 \text{ kg/cm}^3$, $a = 15 \text{ cm}$.

$$l = \left[\frac{Eh^3}{12K(1-\mu^2)} \right]^{1/4}$$

$$l = \left[\frac{3 \times 10^5 \times 18^3}{12 \times 6 (1 - 0.15^2)} \right]^{1/4}$$

$$l = 70.61 \text{ cm}$$

$$\frac{a}{h} = \frac{15}{18} = 0.83 \quad \text{so } \frac{a}{h} < 1.724 \text{ then}$$

$$b = \sqrt{1.6a^2 + h^2} - 0.675h$$

$$= \sqrt{1.6 \times 15^2 + 18^2} - 0.675 \times 18$$

$$b = 14 \text{ cm.}$$

$$3. \quad s_i = 210 \text{ N/mm}^2 ; \quad s_t = 90 \text{ N/mm}^2 ; \quad s_f = 10 \text{ N/mm}^2$$

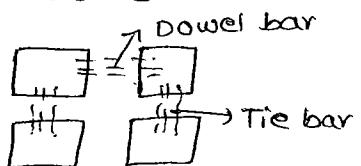
$$\begin{aligned} \text{combination in summer} &= WS + TS - FS \\ &= 210 + 90 - 10 \\ &= 290 \text{ N/mm}^2. \end{aligned}$$

Joints in Rigid pavement :-

Reinforcement is provided only at joints.

Longitudinal joints - Tie bars

Transverse joints - Dowel bar



Types of Transverse joints:

1. Expansion joint
2. contraction joint.

Expansion joint:-

These are provided to allow the expansion of pavement due to raise in temperature with respect to construction temperature.

2.5 cm gap is provided as expansion joint

Spacing of expansion joint

$$L_e = \frac{\delta'}{e(t_2 - t_1)}$$

where

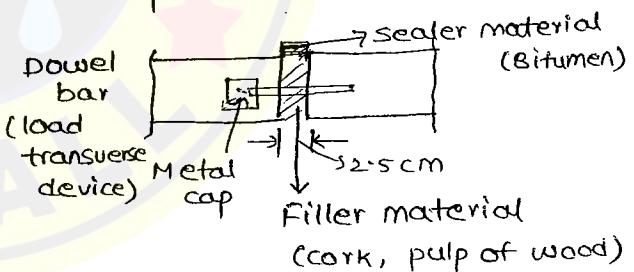
δ' = Max. expansion of slab = $\frac{1}{2}$ of the gap provided

$$\delta' = \frac{2.5}{2} = 1.25 \text{ CM}$$

e = thermal expansion of concrete for $^{\circ}\text{C}$

t_2 = Max. temp in $^{\circ}\text{C}$

t_1 = construction temp in $^{\circ}\text{C}$.



(46)

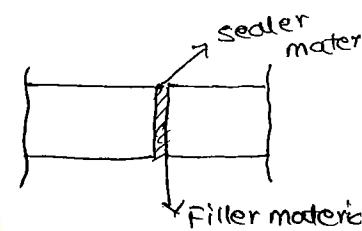
Ex:- the width of expansion joint is 20 mm in C.C. pavement
 the laying temperature is 20°C and maximum temp. in summer
 60°C. Thermal expansion of concrete 10×10^{-6} per °C. The spacing of expansion joint should be

$$\begin{aligned}
 A. \quad L_e &= \frac{\delta}{\epsilon(t_2 - t_1)} \quad \delta = \frac{20}{2} = 10 \text{ mm} \\
 &= \frac{10}{10 \times 10^{-6} (60 - 20)} \\
 &= 25000 \text{ mm} \\
 L_e &= 25 \text{ m}
 \end{aligned}$$

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Contraction Joint :-

The contraction joints are provided to allow the contraction of concrete due to fall in temperature with respect to construction temperature.



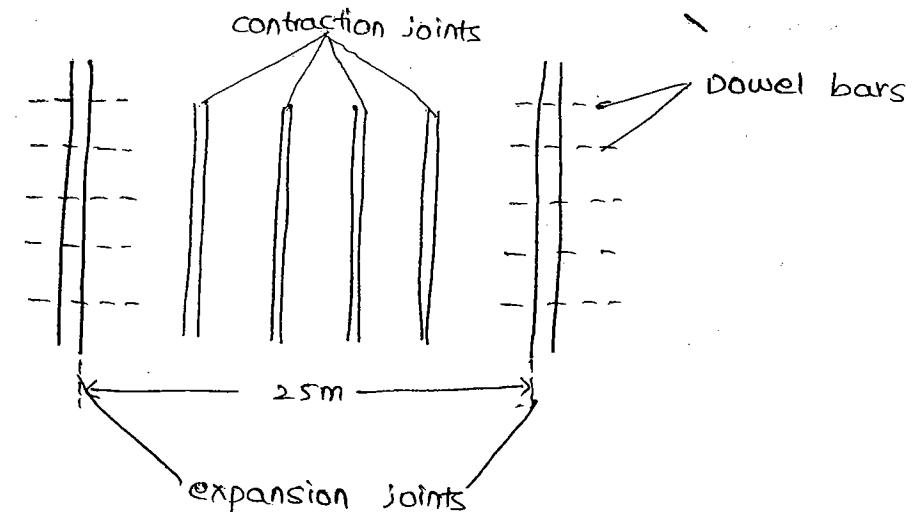
$$L_c = \frac{25c}{wtf} \times 10^4$$

where

s_c = Allowable stress in tension in C.C. kg/cm^2

w = Unit wt. of concrete in kg/m^3

f = coefficient of subgrade restraint.



Longitudinal joint :-

1. The longitudinal joints are required width of pavement is more than 4.5m
2. The area of reinforcement (tie bars) for 1m length of joint

$$A_s = \frac{Bhfw}{s_s \times 100}$$

where

B = width of pavement from edge of pavement to longitudinal joint.

$$B = \frac{\text{width of pavement}}{2}$$

h = thickness of pavement in cm.

f = coefficient of subgrade restraint.

w = unit wt. of concrete in kg/m³

s_s = working tensile stress in steel in kg/cm²

$$\text{Length of the tie bar } (L_t) = \frac{d \times s_s}{2 \times s_b}$$

where

d = Dia of the tie bar in cm

s_b = permissible bond stress of concrete in kg/cm²

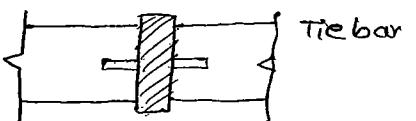
IRC-58 is used for design of rigid pavement.

IRC-58 design of rigid pavements for highways.

1. Legal axial loads in India
2. Single axial = 10.2T
3. Tandem axial = 9T
4. Tridem axial = 24T

cumulative no. of standard axle during design period of pavement

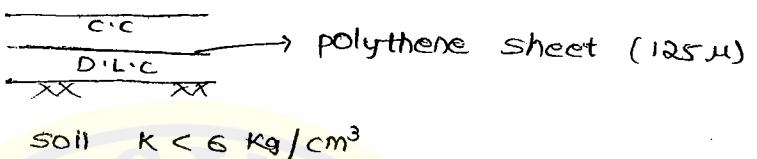
$$c = \frac{365 A [(1+r)^n - 1]}{r}$$



where, A = initial no. of standard axles during design period
 r = annual rate of growth of traffic.
 n = Design life of pavement.

(47)

5. If 'K' value of subgrade is less than 6 kg/cm^3 , the cement concrete pavement should not construct directly on the subgrade soil. A drying lean concrete (DLC) has a sub base course is recommended for construction of cement concrete pavement.



6. A separation membrane of minimum thickness is 125μ is recommended to reduce the friction b/w a D.L.C. layer and cement concrete layer.
7. Recommended dowel bars based on slab thickness

Slab thickness	Dia (cm)	Length (mm)	spacing
20	25	500	250
25	25	500	300
30	32	500	300
35	32	500	300

Ex:- If the load warping (nothing but temperature) and friction stresses in a cement concrete pavement $290, 90, 10 \text{ N/mm}^2$, the critical combination of stresses during summer mid day

A. $W.S + T.S - F.S$

$$290 + 90 - 10$$

$$= 370 \text{ N/mm}^2$$

UNIT - 17

HIGHWAY CONSTRUCTION & MAINTAINANCE

Maintaince of construction and bitumen pavement:-

The various types of bitumen construction are

1. prime coat (Tack coat)
2. Surface dressing and seal coat
3. Grouted (or) penetration type of construction.
 - i) penetration macadam
 - ii) Built up spray grout.
4. pre-mix methods
 - i) bituminous bond macadam (BBM)
 - ii) carpet
 - iii) bituminous concrete
 - iv) sheet asphalt (or) Rolled asphalt
 - v) plastic Asphalt.

Prime coat:-

1. The main object plug in the voids of the forces surface and bonding the existing pavement.
2. Medium curing and slow curing and cut back bitumen are suitable.

Tacke coat:-

1. It is application of bituminous material over existing pavement surface.
2. High viscous material like bitumen is suitable
3. Surface dressing:-

It is a thin various course of pavement to protect base course.

Seal coat:-

- (i) It is a impervious layer provided on the top of the surface of the pavement.
- ii) It will seal the surface not to enter the rain water
- iii) It will develop the skid resultant texture.

Penetration macadam:-

1. It is used as a base course (or) binder course
2. If bitumen penetrated entire depth of compacted aggregate then it is called full grout.
3. If binder material penetrated half of depth of the compacted aggregate then it is called semi-grout.



Built up spray grout:-

It is used for strengthening of existing bituminous pavement.

Total compacted thickness of 75 mm is provided.

Pre mix method:-

Nothing but hot mix process.

Advantages:-

1. It is possible to coat each particle of aggregate with binder material.
2. the quantity of binder material is less when compare to penetration macadam.
3. Strength of the mix is more.

a. BBM:-

1. It is considered to be superior than other base course like WBM with respect to low dispersion characteristics and durability.

b. carpet:-

The coarse aggregate of soils 12.5 to 10 mm mixed with binder materials like bitumen (or) far used as a surface course.

Bituminous concrete:-

1. It is also known as dense graded bituminous construction.
2. It is a combination of coarse aggregate, fine aggregate, filler materials and bitumen.
3. Marshal stability method is used for design.

Sheet (or) Rolled Asphalt:-

It consists of coarse to fine sand mixed with binder material used as a dense layer.

plastic Asphalt:-

It is a combination of fine aggregate, Filler material and binder material. It is suitable for bridge deck slab for absorbing vibrations and has a property of self yielding of cracks without leading.

Maintanance of Roads:-

1. Alligator cracking (or) Map cracking is most common type of failures occur in flexible pavements.
2. This occurs due to swelling and shrinkage of subgrade soil and weakness of base course.
3. Reflection cracking is observed in bituminous overlay over C.C. pavement.
↓
addition of thickness of pavement existing.
4. Mud jacking is remedial measure for mud pumping.
5. Benkelman beam, deflection beams are reflection studies used for design of flexible overlay over the flexible pavement.
6. Scaling in cement concrete pavement indicates overall deterioration of concrete.
7. Capillary cut off is constructed to decrease the capillary rise of ground water.
8. The combination of aggregates screening and Binding material is called W.B.M.

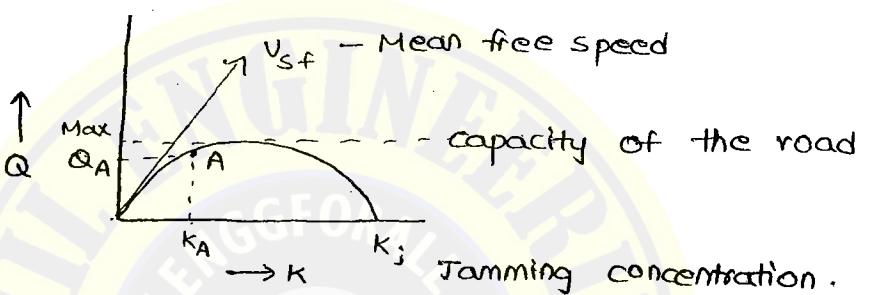
Traffic flow:-

Traffic flow theory is consult with three characteristics of road traffic i.e., speed (v_s) means speed, flow and concentration (k)

concentration (k):-

Concentration is also known as density. It is the no of vehicles present in 1 km length of the road, it is expressed in terms of vehicles / km.

Relation between traffic flow and concentration:-



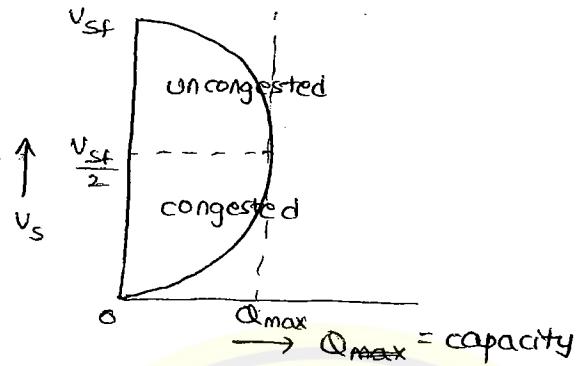
1. The theoretical max. density is called Jamming concentration.
2. If vehicles are packed from end to end and avg. length of the vehicle is 5m then jamming concentration is k_j
3. When vehicles are packed from end to end the flow (Q) is zero.
4. As a concentration increase, flow also increases and reached to max. which is equal to capacity of road.
5. The slope of line joining the origin '0' to the point 'A' on the curve indicates the space mean speed.

$$v_s = \frac{Q_A}{k_A} \quad (\text{or}) \quad \frac{Q}{A}$$

$$Q = v_s \cdot A$$

6. The slope of the line tangential to the curve drawn at origin 'o' represents the mean free speed.
7. The relation is given as $Q = v_{sf} \left[k - \frac{k^2}{k_j} \right]$

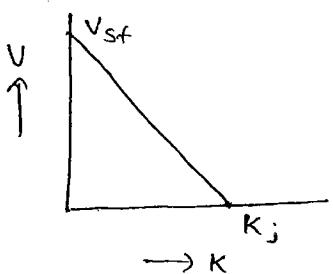
Relation between speed and traffic flow:-



1. When speed is zero, the flow (Q) also zero.
2. when flow is zero, the speed is max. corresponding to mean free - speed (v_{sf})
3. As the flow increases the speed decreases and the flow is reached to the max. corresponding to capacity of the road.
4. the speed corresponding to max. flow is $v_{sf}/2$. the relation between these two

$$Q = k_j \left[k_s - \frac{v_s^2}{v_{sf}} \right]$$

Relation b/w speed and concentration:-



1. when concentration is zero, the speed is max. corresponding to mean free speed (v_{sf})
2. when speed is zero, the concentration is max. corresponding to jamming concentration (k_j).

The relation b/w these two is given as

(50)

$$v_s = v_{sf} \left[1 - \frac{k}{k_j} \right]$$

Note:-

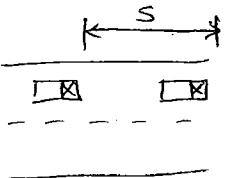
$$Q = Q_{max}$$

$$v_s = v_{sf}$$

$$k = k_j$$

$$Q = v_s \times k, \quad Q_{max} = \frac{v_{sf} \times k_j}{4}$$

$$v_s = \frac{Q}{k}$$



concentration (k) is reciprocal of space head way 's'.

$$v_s = \frac{Q \times s}{1000}$$

where

s = space head way in 'm'.

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If time head way 'h' then the relation is

$$s = \frac{h}{3600} \times v_s \times 1000, \quad h = \text{sec}$$

Ex:- The speed density relationship on a given section of the road is given has $v_s = 70 - 0.7k$ then find capacity of the road.

A. This equation in the form of $v_s = v_{sf} \left(1 - \frac{k}{k_j} \right)$
compare these two equations

$$v_s = 70 \left(1 - \frac{0.7}{70} k \right)$$

$$v_s = v_{sf} \left(1 - \frac{k}{k_j} \right)$$

$$v_{sf} = 70 \text{ kmph} \quad k_j = \frac{70}{0.7}$$

then capacity of the road $Q_{max} = v_{sf} \times k_j$

$$= 70 \times \frac{70}{0.7} \times \frac{1}{4}$$

$$= 1750 \text{ veh/hr}$$